

## 1. General Description

This Document contains the log data of a read out logfile. It shows what happened with the specified vbar unit during the latest time

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|------------------------|-------------------------------------|
| Version of PC Software | <b>5.3.2b 31.12.2012</b>            |
| Date                   | <b>Fri Jun 16 15:10:06 EET 2017</b> |
| Serial                 | <b>1410043376</b>                   |
| Prod Date              | <b>21.7.2014 10:23</b>              |
| Firmware               | <b>5.3</b>                          |
| Patchlevel             | <b>4</b>                            |

## 2. Chronological List of Events

|   |      |                                   |   |
|---|------|-----------------------------------|---|
| ✔ | 0:00 | Reset Reason: Power On            | This happens if power is applied to the VBar unit. Usually this is ok, but it shall never happen in operational mode. So if a reset happens during flight, this points to a power problem. During flight the power on reset results in a warmstart. If a coldstart happens during flight, the power loss was more than 5 Seconds      |
| ▶ | 0:00 | Bank 0 Loaded                     | Bank 0 was loaded from the non volatile memory. This can be triggered my manual backswitch from the userinterface as well as in flight if bank switch is programmed to the aux channel. On Startup the Bank 0 is loaded by default.   |
| ▶ | 0:00 | Governor Mode Throttle            | Governor off, the servo moves with the throttle input channel   |
| ▶ | 0:07 | Calibration Finished              | At each Coldstart, the sensor and RC Values are calibrated to the actual seen values. If the calibration is finished, this message confirms the storage of data into the internal non volatile calibration memory   |
| ✔ | 0:17 | Good Health Message (10sec)       | This Message describes the good health state. That means, that the VBar unit does not see any error or Info Message in the last 10 Seconds.   |
| ✔ | 0:27 | Good Health Message (10sec)       | This Message describes the good health state. That means, that the VBar unit does not see any error or Info Message in the last 10 Seconds.   |
| ✔ | 0:37 | Good Health Message (10sec)       | This Message describes the good health state. That means, that the VBar unit does not see any error or Info Message in the last 10 Seconds.   |
| ✔ | 0:47 | Good Health Message (10sec)       | This Message describes the good health state. That means, that the VBar unit does not see any error or Info Message in the last 10 Seconds.   |
| ✔ | 0:57 | Good Health Message (10sec)       | This Message describes the good health state. That means, that the VBar unit does not see any error or Info Message in the last 10 Seconds.   |
| ✔ | 1:07 | Good Health Message (10sec)       | This Message describes the good health state. That means, that the VBar unit does not see any error or Info Message in the last 10 Seconds.   |
| ✔ | 1:17 | Good Health Message (10sec)       | This Message describes the good health state. That means, that the VBar unit does not see any error or Info Message in the last 10 Seconds.   |
| ✔ | 1:27 | Good Health Message (10sec)       | This Message describes the good health state. That means, that the VBar unit does not see any error or Info Message in the last 10 Seconds.   |
| ✔ | 1:37 | Good Health Message (10sec)       | This Message describes the good health state. That means, that the VBar unit does not see any error or Info Message in the last 10 Seconds.   |
| ▶ | 1:45 | Raised Vibration Level            | There was detected a raised level of Vibration. Since the vibration detector has to decide which signal is vibration and chis is the intended measurement signal, this can happen sometimes on hard 3d moves. It shall not happen all the time. If this error is reported repeditly very often, check the heli for vibration sources. |
| ▶ | 1:55 | Raised Vibration Level            | There was detected a raised level of Vibration. Since the vibration detector has to decide which signal is vibration and chis is the intended measurement signal, this can happen sometimes on hard 3d moves. It shall not happen all the time. If this error is reported repeditly very often, check the heli for vibration sources. |
| ✔ | 2:05 | Good Health Message (10sec)       | This Message describes the good health state. That means, that the VBar unit does not see any error or Info Message in the last 10 Seconds.   |
| ▶ | 2:07 | Governor ON                       | Governor switched to mode ON  |
| ▶ | 2:07 | Governor is at Low Throttle Limit | There is a defined low limit, that the Governor will not fall below. lth this Limit is reached, this Info Message is issued. The Message is issued once for each touch of the limit. If the limit is touched, it means that your headspeed will be higher than programmed.  |
| ▶ | 2:13 | Governor is at Low Throttle Limit | There is a defined low limit, that the Governor will not fall below. lth this Limit is reached, this Info Message is issued. The Message is issued once for each touch of the limit. If the limit is touched, it means that your headspeed will be higher than programmed.  |
| ▶ | 2:14 | Raised Vibration Level            | There was detected a raised level of Vibration. Since the vibration detector has to decide which signal is vibration and chis is the intended measurement signal, this can happen sometimes on hard 3d moves. It shall not happen all the time. If this error is reported repeditly very often, check the heli for vibration sources. |
| ▶ | 2:14 | Governor is at Low Throttle Limit | There is a defined low limit, that the Governor will not fall below. lth this Limit is reached, this Info Message is issued. The Message is issued once for each touch of the limit. If the limit is touched, it means that your headspeed will be higher than programmed.  |
| ▶ | 2:15 | Governor is at Low Throttle Limit | There is a defined low limit, that the Governor will not fall below. lth this Limit is reached, this Info Message is issued. The Message is issued once for each touch of the limit. If the limit is touched, it means that your headspeed will be higher than programmed.  |
| ▶ | 2:17 | Governor is at Low Throttle Limit | There is a defined low limit, that the Governor will not fall below. lth this Limit is reached, this Info Message is issued. The Message is issued once for each touch of the limit. If the limit is touched, it means that your headspeed will be higher than programmed.  |
| ▶ | 2:18 | Governor is at Low Throttle Limit | There is a defined low limit, that the Governor will not fall below. lth this Limit is reached, this Info Message is issued. The Message is issued once for each touch of the limit. If the limit is touched, it means that your headspeed will be higher than programmed.  |
| ▶ | 2:19 | Governor is at Low Throttle Limit | There is a defined low limit, that the Governor will not fall below. lth this Limit is reached, this Info Message is issued. The Message is issued once for each touch of the limit. If the limit is touched, it means that your headspeed will be higher than programmed.  |



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| ▲ | 6:05 | High Vibration Level              | The control loop suffers from a high vibration level, that starts to render the sensors blind. Save flying is possible, but the stability will be degraded. Additionally slow drifts that happen may be caused by vibrations.  |
| ✖ | 6:15 | Extreme Vibration Level           | Vibrations are extreme. That means, that the measurement signal is much lower than the signal level of the vibrations. No usable flying is possible with this level. Everything has to be checked and extended tests are needed to isolate and eliminate the source of vibrations  |
| ▲ | 6:24 | High Vibration Level              | The control loop suffers from a high vibration level, that starts to render the sensors blind. Save flying is possible, but the stability will be degraded. Additionally slow drifts that happen may be caused by vibrations.  |
| ✖ | 6:34 | Extreme Vibration Level           | Vibrations are extreme. That means, that the measurement signal is much lower than the signal level of the vibrations. No usable flying is possible with this level. Everything has to be checked and extended tests are needed to isolate and eliminate the source of vibrations  |
| ▶ | 6:40 | Governor is at Low Throttle Limit | There is a defined low limit, that the Governor will not fall below. If this Limit is reached, this Info Message is issued. The Message is issued once for each touch of the limit. If the limit is touched, it means that your headspeed will be higher than programmed.  |
| ✖ | 6:43 | Extreme Vibration Level           | Vibrations are extreme. That means, that the measurement signal is much lower than the signal level of the vibrations. No usable flying is possible with this level. Everything has to be checked and extended tests are needed to isolate and eliminate the source of vibrations  |
| ▶ | 6:53 | Raised Vibration Level            | There was detected a raised level of Vibration. Since the vibration detector has to decide which signal is vibration and this is the intended measurement signal, this can happen sometimes on hard 3d moves. It shall not happen all the time. If this error is reported repeatedly very often, check the heli for vibration sources. |
| ▲ | 7:03 | High Vibration Level              | The control loop suffers from a high vibration level, that starts to render the sensors blind. Save flying is possible, but the stability will be degraded. Additionally slow drifts that happen may be caused by vibrations.  |
| ▶ | 7:12 | Raised Vibration Level            | There was detected a raised level of Vibration. Since the vibration detector has to decide which signal is vibration and this is the intended measurement signal, this can happen sometimes on hard 3d moves. It shall not happen all the time. If this error is reported repeatedly very often, check the heli for vibration sources. |
| ▲ | 7:22 | High Vibration Level              | The control loop suffers from a high vibration level, that starts to render the sensors blind. Save flying is possible, but the stability will be degraded. Additionally slow drifts that happen may be caused by vibrations.  |
| ▲ | 7:32 | High Vibration Level              | The control loop suffers from a high vibration level, that starts to render the sensors blind. Save flying is possible, but the stability will be degraded. Additionally slow drifts that happen may be caused by vibrations.  |
| ▲ | 7:41 | High Vibration Level              | The control loop suffers from a high vibration level, that starts to render the sensors blind. Save flying is possible, but the stability will be degraded. Additionally slow drifts that happen may be caused by vibrations.  |
| ▲ | 7:51 | High Vibration Level              | The control loop suffers from a high vibration level, that starts to render the sensors blind. Save flying is possible, but the stability will be degraded. Additionally slow drifts that happen may be caused by vibrations.  |
| ▲ | 8:00 | High Vibration Level              | The control loop suffers from a high vibration level, that starts to render the sensors blind. Save flying is possible, but the stability will be degraded. Additionally slow drifts that happen may be caused by vibrations.  |
| ▶ | 8:10 | Raised Vibration Level            | There was detected a raised level of Vibration. Since the vibration detector has to decide which signal is vibration and this is the intended measurement signal, this can happen sometimes on hard 3d moves. It shall not happen all the time. If this error is reported repeatedly very often, check the heli for vibration sources. |
| ▶ | 8:20 | Raised Vibration Level            | There was detected a raised level of Vibration. Since the vibration detector has to decide which signal is vibration and this is the intended measurement signal, this can happen sometimes on hard 3d moves. It shall not happen all the time. If this error is reported repeatedly very often, check the heli for vibration sources. |
| ▶ | 8:29 | Raised Vibration Level            | There was detected a raised level of Vibration. Since the vibration detector has to decide which signal is vibration and this is the intended measurement signal, this can happen sometimes on hard 3d moves. It shall not happen all the time. If this error is reported repeatedly very often, check the heli for vibration sources. |
| ▲ | 8:39 | High Vibration Level              | The control loop suffers from a high vibration level, that starts to render the sensors blind. Save flying is possible, but the stability will be degraded. Additionally slow drifts that happen may be caused by vibrations.  |
| ✖ | 8:49 | Extreme Vibration Level           | Vibrations are extreme. That means, that the measurement signal is much lower than the signal level of the vibrations. No usable flying is possible with this level. Everything has to be checked and extended tests are needed to isolate and eliminate the source of vibrations  |
| ✖ | 8:58 | Extreme Vibration Level           | Vibrations are extreme. That means, that the measurement signal is much lower than the signal level of the vibrations. No usable flying is possible with this level. Everything has to be checked and extended tests are needed to isolate and eliminate the source of vibrations  |
| ▶ | 9:08 | Raised Vibration Level            | There was detected a raised level of Vibration. Since the vibration detector has to decide which signal is vibration and this is the intended measurement signal, this can happen sometimes on hard 3d moves. It shall not happen all the time. If this error is reported repeatedly very often, check the heli for vibration sources. |
| ▶ | 9:17 | Raised Vibration Level            | There was detected a raised level of Vibration. Since the vibration detector has to decide which signal is vibration and this is the intended measurement signal, this can happen sometimes on hard 3d moves. It shall not happen all the time. If this error is reported repeatedly very often, check the heli for vibration sources. |
| ▲ | 9:27 | High Vibration Level              | The control loop suffers from a high vibration level, that starts to render the sensors blind. Save flying is possible, but the stability will be degraded. Additionally slow drifts that happen may be caused by vibrations.  |
| ▶ | 9:28 | Governor Mode Throttle            | Governor off, the servo moves with the throttle input channel  |
| ✖ | 9:37 | Extreme Vibration Level           | Vibrations are extreme. That means, that the measurement signal is much lower than the signal level of the vibrations. No usable flying is possible with this level. Everything has to be checked and extended tests are needed to isolate and eliminate the source of vibrations  |

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| ▶ | 9:46 | Raised Vibration Level      | There was detected a raised level of Vibration. Since the vibration detector has to decide which signal is vibration and this is the intended measurement signal, this can happen sometimes on hard 3d moves. It shall not happen all the time. If this error is reported repeatedly very often, check the heli for vibration sources. |
| ▶ | 9:56 | Raised Vibration Level      | There was detected a raised level of Vibration. Since the vibration detector has to decide which signal is vibration and this is the intended measurement signal, this can happen sometimes on hard 3d moves. It shall not happen all the time. If this error is reported repeatedly very often, check the heli for vibration sources. |
| ✔ | 0:00 | Coldstart                   | A Coldstart is done on the beginning of each switch on time. A Coldstart can happen only, if the VBar Units is disconnected from power for more than 5 Seconds.  |
| ✔ | 0:00 | Reset Reason: Power On      | This happens if power is applied to the VBar unit. Usually this is ok, but it shall never happen in operational mode. So if a reset happens during flight, this points to a power problem. During flight the power on reset results in a warmstart. If a coldstart happens during flight, the power loss was more than 5 Seconds       |
| ▶ | 0:00 | Bank 0 Loaded               | Bank 0 was loaded from the non volatile memory. This can be triggered my manual backswitch from the userinterface as well as in flight if bank switch is programmed to the aux channel. On Startup the Bank 0 is loaded by default.  |
| ▶ | 0:00 | Governor Mode Throttle      | Governor off, the servo moves with the throttle input channel  |
| ▶ | 0:06 | Calibration Finished        | At each Coldstart, the sensor and RC Values are calibrated to the actual seen values. If the calibration is finished, this message confirms the storage of data into the internal non volatile calibration memory  |
| ✔ | 0:00 | Coldstart                   | A Coldstart is done on the beginning of each switch on time. A Coldstart can happen only, if the VBar Units is disconnected from power for more than 5 Seconds.  |
| ✔ | 0:00 | Reset Reason: Power On      | This happens if power is applied to the VBar unit. Usually this is ok, but it shall never happen in operational mode. So if a reset happens during flight, this points to a power problem. During flight the power on reset results in a warmstart. If a coldstart happens during flight, the power loss was more than 5 Seconds       |
| ▶ | 0:00 | Bank 0 Loaded               | Bank 0 was loaded from the non volatile memory. This can be triggered my manual backswitch from the userinterface as well as in flight if bank switch is programmed to the aux channel. On Startup the Bank 0 is loaded by default.  |
| ▶ | 0:00 | Governor Mode Throttle      | Governor off, the servo moves with the throttle input channel  |
| ▶ | 0:06 | Calibration Finished        | At each Coldstart, the sensor and RC Values are calibrated to the actual seen values. If the calibration is finished, this message confirms the storage of data into the internal non volatile calibration memory  |
| ✔ | 0:16 | Good Health Message (10sec) | This Message describes the good health state. That means, that the VBar unit does not see any error or Info Message in the last 10 Seconds.  |
| ✔ | 0:26 | Good Health Message (10sec) | This Message describes the good health state. That means, that the VBar unit does not see any error or Info Message in the last 10 Seconds.  |
| ✔ | 0:36 | Good Health Message (10sec) | This Message describes the good health state. That means, that the VBar unit does not see any error or Info Message in the last 10 Seconds.  |
| ✔ | 0:46 | Good Health Message (10sec) | This Message describes the good health state. That means, that the VBar unit does not see any error or Info Message in the last 10 Seconds.  |
| ✔ | 0:56 | Good Health Message (10sec) | This Message describes the good health state. That means, that the VBar unit does not see any error or Info Message in the last 10 Seconds.  |
| ✔ | 1:06 | Good Health Message (10sec) | This Message describes the good health state. That means, that the VBar unit does not see any error or Info Message in the last 10 Seconds.  |
| ✔ | 1:16 | Good Health Message (10sec) | This Message describes the good health state. That means, that the VBar unit does not see any error or Info Message in the last 10 Seconds.  |
| ✔ | 1:26 | Good Health Message (10sec) | This Message describes the good health state. That means, that the VBar unit does not see any error or Info Message in the last 10 Seconds.  |
| ✔ | 1:36 | Good Health Message (10sec) | This Message describes the good health state. That means, that the VBar unit does not see any error or Info Message in the last 10 Seconds.  |
| ✔ | 1:46 | Good Health Message (10sec) | This Message describes the good health state. That means, that the VBar unit does not see any error or Info Message in the last 10 Seconds.  |
| ✔ | 1:56 | Good Health Message (10sec) | This Message describes the good health state. That means, that the VBar unit does not see any error or Info Message in the last 10 Seconds.  |
| ✔ | 2:06 | Good Health Message (10sec) | This Message describes the good health state. That means, that the VBar unit does not see any error or Info Message in the last 10 Seconds.  |
| ✔ | 2:16 | Good Health Message (10sec) | This Message describes the good health state. That means, that the VBar unit does not see any error or Info Message in the last 10 Seconds.  |
| ✔ | 2:26 | Good Health Message (10sec) | This Message describes the good health state. That means, that the VBar unit does not see any error or Info Message in the last 10 Seconds.  |
| ✔ | 2:36 | Good Health Message (10sec) | This Message describes the good health state. That means, that the VBar unit does not see any error or Info Message in the last 10 Seconds.  |

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| ▶ | 2:43 | Raised Vibration Level            | There was detected a raised level of Vibration. Since the vibration detector has to decide which signal is vibration and this is the intended measurement signal, this can happen sometimes on hard 3d moves. It shall not happen all the time. If this error is reported repeatedly very often, check the heli for vibration sources. |
| ✔ | 2:53 | Good Health Message (10sec)       | This Message describes the good health state. That means, that the VBar unit does not see any error or Info Message in the last 10 Seconds.  |
| ✔ | 3:03 | Good Health Message (10sec)       | This Message describes the good health state. That means, that the VBar unit does not see any error or Info Message in the last 10 Seconds.  |
| ✔ | 3:13 | Good Health Message (10sec)       | This Message describes the good health state. That means, that the VBar unit does not see any error or Info Message in the last 10 Seconds.  |
| ✔ | 3:23 | Good Health Message (10sec)       | This Message describes the good health state. That means, that the VBar unit does not see any error or Info Message in the last 10 Seconds.  |
| ✔ | 3:33 | Good Health Message (10sec)       | This Message describes the good health state. That means, that the VBar unit does not see any error or Info Message in the last 10 Seconds.  |
| ✔ | 3:43 | Good Health Message (10sec)       | This Message describes the good health state. That means, that the VBar unit does not see any error or Info Message in the last 10 Seconds.  |
| ▶ | 3:50 | Raised Vibration Level            | There was detected a raised level of Vibration. Since the vibration detector has to decide which signal is vibration and this is the intended measurement signal, this can happen sometimes on hard 3d moves. It shall not happen all the time. If this error is reported repeatedly very often, check the heli for vibration sources. |
| ▶ | 4:00 | Raised Vibration Level            | There was detected a raised level of Vibration. Since the vibration detector has to decide which signal is vibration and this is the intended measurement signal, this can happen sometimes on hard 3d moves. It shall not happen all the time. If this error is reported repeatedly very often, check the heli for vibration sources. |
| ▶ | 4:01 | Governor ON                       | Governor switched to mode ON   |
| ▶ | 4:01 | Governor is at Low Throttle Limit | There is a defined low limit, that the Governor will not fall below. If this Limit is reached, this Info Message is issued. The Message is issued once for each touch of the limit. If the limit is touched, it means that your headspeed will be higher than programmed.  |
| ▶ | 4:09 | Governor is at Low Throttle Limit | There is a defined low limit, that the Governor will not fall below. If this Limit is reached, this Info Message is issued. The Message is issued once for each touch of the limit. If the limit is touched, it means that your headspeed will be higher than programmed.  |
| ▶ | 4:10 | Raised Vibration Level            | There was detected a raised level of Vibration. Since the vibration detector has to decide which signal is vibration and this is the intended measurement signal, this can happen sometimes on hard 3d moves. It shall not happen all the time. If this error is reported repeatedly very often, check the heli for vibration sources. |
| ▶ | 4:10 | Governor is at Low Throttle Limit | There is a defined low limit, that the Governor will not fall below. If this Limit is reached, this Info Message is issued. The Message is issued once for each touch of the limit. If the limit is touched, it means that your headspeed will be higher than programmed.  |
| ▶ | 4:11 | Governor is at Low Throttle Limit | There is a defined low limit, that the Governor will not fall below. If this Limit is reached, this Info Message is issued. The Message is issued once for each touch of the limit. If the limit is touched, it means that your headspeed will be higher than programmed.  |
| ▶ | 4:12 | Governor is at Low Throttle Limit | There is a defined low limit, that the Governor will not fall below. If this Limit is reached, this Info Message is issued. The Message is issued once for each touch of the limit. If the limit is touched, it means that your headspeed will be higher than programmed.  |
| ▶ | 4:15 | Governor is at Low Throttle Limit | There is a defined low limit, that the Governor will not fall below. If this Limit is reached, this Info Message is issued. The Message is issued once for each touch of the limit. If the limit is touched, it means that your headspeed will be higher than programmed.  |
| ▶ | 4:16 | Governor is at Low Throttle Limit | There is a defined low limit, that the Governor will not fall below. If this Limit is reached, this Info Message is issued. The Message is issued once for each touch of the limit. If the limit is touched, it means that your headspeed will be higher than programmed.  |
| ▶ | 4:17 | Governor is at Low Throttle Limit | There is a defined low limit, that the Governor will not fall below. If this Limit is reached, this Info Message is issued. The Message is issued once for each touch of the limit. If the limit is touched, it means that your headspeed will be higher than programmed.  |
| ▶ | 4:19 | Raised Vibration Level            | There was detected a raised level of Vibration. Since the vibration detector has to decide which signal is vibration and this is the intended measurement signal, this can happen sometimes on hard 3d moves. It shall not happen all the time. If this error is reported repeatedly very often, check the heli for vibration sources. |
| ▶ | 4:20 | Governor is at Low Throttle Limit | There is a defined low limit, that the Governor will not fall below. If this Limit is reached, this Info Message is issued. The Message is issued once for each touch of the limit. If the limit is touched, it means that your headspeed will be higher than programmed.  |
| ▶ | 4:21 | Governor is at Low Throttle Limit | There is a defined low limit, that the Governor will not fall below. If this Limit is reached, this Info Message is issued. The Message is issued once for each touch of the limit. If the limit is touched, it means that your headspeed will be higher than programmed.  |
| ▶ | 4:29 | Raised Vibration Level            | There was detected a raised level of Vibration. Since the vibration detector has to decide which signal is vibration and this is the intended measurement signal, this can happen sometimes on hard 3d moves. It shall not happen all the time. If this error is reported repeatedly very often, check the heli for vibration sources. |
| ⚠ | 4:38 | High Vibration Level              | The control loop suffers from a high vibration level, that starts to render the sensors blind. Safe flying is possible, but the stability will be degraded. Additionally slow drifts that happen may be caused by vibrations.  |
| ⚠ | 4:48 | High Vibration Level              | The control loop suffers from a high vibration level, that starts to render the sensors blind. Safe flying is possible, but the stability will be degraded. Additionally slow drifts that happen may be caused by vibrations.  |

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| ▶ | 4:58 | Raised Vibration Level            | There was detected a raised level of Vibration. Since the vibration detector has to decide which signal is vibration and this is the intended measurement signal, this can happen sometimes on hard 3d moves. It shall not happen all the time. If this error is reported repeatedly very often, check the heli for vibration sources. |
| ⚠ | 5:07 | High Vibration Level              | The control loop suffers from a high vibration level, that starts to render the sensors blind. Save flying is possible, but the stability will be degraded. Additionally slow drifts that happen may be caused by vibrations.  |
| ▶ | 5:17 | Raised Vibration Level            | There was detected a raised level of Vibration. Since the vibration detector has to decide which signal is vibration and this is the intended measurement signal, this can happen sometimes on hard 3d moves. It shall not happen all the time. If this error is reported repeatedly very often, check the heli for vibration sources. |
| ✖ | 5:27 | Extreme Vibration Level           | Vibrations are extreme. That means, that the measurement signal is much lower than the signal level of the vibrations. No usable flying is possible with this level. Everything has to be checked and extended tests are needed to isolate and eliminate the source of vibrations  |
| ▶ | 5:36 | Raised Vibration Level            | There was detected a raised level of Vibration. Since the vibration detector has to decide which signal is vibration and this is the intended measurement signal, this can happen sometimes on hard 3d moves. It shall not happen all the time. If this error is reported repeatedly very often, check the heli for vibration sources. |
| ⚠ | 5:46 | High Vibration Level              | The control loop suffers from a high vibration level, that starts to render the sensors blind. Save flying is possible, but the stability will be degraded. Additionally slow drifts that happen may be caused by vibrations.  |
| ⚠ | 5:55 | High Vibration Level              | The control loop suffers from a high vibration level, that starts to render the sensors blind. Save flying is possible, but the stability will be degraded. Additionally slow drifts that happen may be caused by vibrations.  |
| ⚠ | 6:05 | High Vibration Level              | The control loop suffers from a high vibration level, that starts to render the sensors blind. Save flying is possible, but the stability will be degraded. Additionally slow drifts that happen may be caused by vibrations.  |
| ⚠ | 6:15 | High Vibration Level              | The control loop suffers from a high vibration level, that starts to render the sensors blind. Save flying is possible, but the stability will be degraded. Additionally slow drifts that happen may be caused by vibrations.  |
| ⚠ | 6:24 | High Vibration Level              | The control loop suffers from a high vibration level, that starts to render the sensors blind. Save flying is possible, but the stability will be degraded. Additionally slow drifts that happen may be caused by vibrations.  |
| ⚠ | 6:34 | High Vibration Level              | The control loop suffers from a high vibration level, that starts to render the sensors blind. Save flying is possible, but the stability will be degraded. Additionally slow drifts that happen may be caused by vibrations.  |
| ⚠ | 6:43 | High Vibration Level              | The control loop suffers from a high vibration level, that starts to render the sensors blind. Save flying is possible, but the stability will be degraded. Additionally slow drifts that happen may be caused by vibrations.  |
| ⚠ | 6:53 | High Vibration Level              | The control loop suffers from a high vibration level, that starts to render the sensors blind. Save flying is possible, but the stability will be degraded. Additionally slow drifts that happen may be caused by vibrations.  |
| ⚠ | 7:03 | High Vibration Level              | The control loop suffers from a high vibration level, that starts to render the sensors blind. Save flying is possible, but the stability will be degraded. Additionally slow drifts that happen may be caused by vibrations.  |
| ⚠ | 7:12 | High Vibration Level              | The control loop suffers from a high vibration level, that starts to render the sensors blind. Save flying is possible, but the stability will be degraded. Additionally slow drifts that happen may be caused by vibrations.  |
| ✖ | 7:22 | Extreme Vibration Level           | Vibrations are extreme. That means, that the measurement signal is much lower than the signal level of the vibrations. No usable flying is possible with this level. Everything has to be checked and extended tests are needed to isolate and eliminate the source of vibrations  |
| ⚠ | 7:32 | High Vibration Level              | The control loop suffers from a high vibration level, that starts to render the sensors blind. Save flying is possible, but the stability will be degraded. Additionally slow drifts that happen may be caused by vibrations.  |
| ⚠ | 7:41 | High Vibration Level              | The control loop suffers from a high vibration level, that starts to render the sensors blind. Save flying is possible, but the stability will be degraded. Additionally slow drifts that happen may be caused by vibrations.  |
| ⚠ | 7:51 | High Vibration Level              | The control loop suffers from a high vibration level, that starts to render the sensors blind. Save flying is possible, but the stability will be degraded. Additionally slow drifts that happen may be caused by vibrations.  |
| ⚠ | 8:00 | High Vibration Level              | The control loop suffers from a high vibration level, that starts to render the sensors blind. Save flying is possible, but the stability will be degraded. Additionally slow drifts that happen may be caused by vibrations.  |
| ⚠ | 8:10 | High Vibration Level              | The control loop suffers from a high vibration level, that starts to render the sensors blind. Save flying is possible, but the stability will be degraded. Additionally slow drifts that happen may be caused by vibrations.  |
| ✖ | 8:20 | Extreme Vibration Level           | Vibrations are extreme. That means, that the measurement signal is much lower than the signal level of the vibrations. No usable flying is possible with this level. Everything has to be checked and extended tests are needed to isolate and eliminate the source of vibrations  |
| ✖ | 8:29 | Extreme Vibration Level           | Vibrations are extreme. That means, that the measurement signal is much lower than the signal level of the vibrations. No usable flying is possible with this level. Everything has to be checked and extended tests are needed to isolate and eliminate the source of vibrations  |
| ✖ | 8:39 | Extreme Vibration Level           | Vibrations are extreme. That means, that the measurement signal is much lower than the signal level of the vibrations. No usable flying is possible with this level. Everything has to be checked and extended tests are needed to isolate and eliminate the source of vibrations  |
| ▶ | 8:48 | Governor is at Low Throttle Limit | There is a defined low limit, that the Governor will not fall below. If this Limit is reached, this Info Message is issued. The Message is issued once for each touch of the limit. If the limit is touched, it means that your headspeed will be higher than programmed.  |
| ⚠ | 8:49 | High Vibration Level              | The control loop suffers from a high vibration level, that starts to render the sensors blind. Save flying is possible, but the stability will be degraded. Additionally slow drifts that happen may be caused by vibrations.  |

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| ▲ | 8:58  | High Vibration Level              | The control loop suffers from a high vibration level, that starts to render the sensors blind. Save flying is possible, but the stability will be degraded. Additionally slow drifts that happen may be caused by vibrations.  |
| ▲ | 9:08  | High Vibration Level              | The control loop suffers from a high vibration level, that starts to render the sensors blind. Save flying is possible, but the stability will be degraded. Additionally slow drifts that happen may be caused by vibrations.  |
| ▶ | 9:17  | Raised Vibration Level            | There was detected a raised level of Vibration. Since the vibration detector has to decide which signal is vibration and this is the intended measurement signal, this can happen sometimes on hard 3d moves. It shall not happen all the time. If this error is reported repeatedly very often, check the heli for vibration sources. |
| ▶ | 9:27  | Raised Vibration Level            | There was detected a raised level of Vibration. Since the vibration detector has to decide which signal is vibration and this is the intended measurement signal, this can happen sometimes on hard 3d moves. It shall not happen all the time. If this error is reported repeatedly very often, check the heli for vibration sources. |
| ▲ | 9:37  | High Vibration Level              | The control loop suffers from a high vibration level, that starts to render the sensors blind. Save flying is possible, but the stability will be degraded. Additionally slow drifts that happen may be caused by vibrations.  |
| ▲ | 9:46  | High Vibration Level              | The control loop suffers from a high vibration level, that starts to render the sensors blind. Save flying is possible, but the stability will be degraded. Additionally slow drifts that happen may be caused by vibrations.  |
| ▲ | 9:56  | High Vibration Level              | The control loop suffers from a high vibration level, that starts to render the sensors blind. Save flying is possible, but the stability will be degraded. Additionally slow drifts that happen may be caused by vibrations.  |
| ✖ | 10:05 | Extreme Vibration Level           | Vibrations are extreme. That means, that the measurement signal is much lower than the signal level of the vibrations. No usable flying is possible with this level. Everything has to be checked and extended tests are needed to isolate and eliminate the source of vibrations  |
| ▶ | 10:15 | Raised Vibration Level            | There was detected a raised level of Vibration. Since the vibration detector has to decide which signal is vibration and this is the intended measurement signal, this can happen sometimes on hard 3d moves. It shall not happen all the time. If this error is reported repeatedly very often, check the heli for vibration sources. |
| ▶ | 10:25 | Raised Vibration Level            | There was detected a raised level of Vibration. Since the vibration detector has to decide which signal is vibration and this is the intended measurement signal, this can happen sometimes on hard 3d moves. It shall not happen all the time. If this error is reported repeatedly very often, check the heli for vibration sources. |
| ▶ | 10:34 | Raised Vibration Level            | There was detected a raised level of Vibration. Since the vibration detector has to decide which signal is vibration and this is the intended measurement signal, this can happen sometimes on hard 3d moves. It shall not happen all the time. If this error is reported repeatedly very often, check the heli for vibration sources. |
| ▶ | 10:44 | Raised Vibration Level            | There was detected a raised level of Vibration. Since the vibration detector has to decide which signal is vibration and this is the intended measurement signal, this can happen sometimes on hard 3d moves. It shall not happen all the time. If this error is reported repeatedly very often, check the heli for vibration sources. |
| ▲ | 10:54 | High Vibration Level              | The control loop suffers from a high vibration level, that starts to render the sensors blind. Save flying is possible, but the stability will be degraded. Additionally slow drifts that happen may be caused by vibrations.  |
| ▲ | 11:03 | High Vibration Level              | The control loop suffers from a high vibration level, that starts to render the sensors blind. Save flying is possible, but the stability will be degraded. Additionally slow drifts that happen may be caused by vibrations.  |
| ▶ | 11:13 | Raised Vibration Level            | There was detected a raised level of Vibration. Since the vibration detector has to decide which signal is vibration and this is the intended measurement signal, this can happen sometimes on hard 3d moves. It shall not happen all the time. If this error is reported repeatedly very often, check the heli for vibration sources. |
| ▲ | 11:22 | High Vibration Level              | The control loop suffers from a high vibration level, that starts to render the sensors blind. Save flying is possible, but the stability will be degraded. Additionally slow drifts that happen may be caused by vibrations.  |
| ▶ | 11:32 | Raised Vibration Level            | There was detected a raised level of Vibration. Since the vibration detector has to decide which signal is vibration and this is the intended measurement signal, this can happen sometimes on hard 3d moves. It shall not happen all the time. If this error is reported repeatedly very often, check the heli for vibration sources. |
| ▶ | 11:36 | Governor Mode Throttle            | Governor off, the servo moves with the throttle input channel  |
| ✖ | 11:41 | Aileron Sensor Value out of Range | The Sensor delivers Values that are not trustful. Rotational rates, that will create this values are usually not possible in air. The Sensor may be defective. This can happen in certain cases if the heli is handled on ground, or on very hard landings or very extreme Vibrations.   |
| ✖ | 11:42 | Extreme Vibration Level           | Vibrations are extreme. That means, that the measurement signal is much lower than the signal level of the vibrations. No usable flying is possible with this level. Everything has to be checked and extended tests are needed to isolate and eliminate the source of vibrations  |
| ✔ | 11:52 | Good Health Message (10sec)       | This Message describes the good health state. That means, that the VBar unit does not see any error or Info Message in the last 10 Seconds.  |
| ✔ | 12:02 | Good Health Message (10sec)       | This Message describes the good health state. That means, that the VBar unit does not see any error or Info Message in the last 10 Seconds.  |
| ✔ | 12:12 | Good Health Message (10sec)       | This Message describes the good health state. That means, that the VBar unit does not see any error or Info Message in the last 10 Seconds.  |
| ✔ | 0:00  | Coldstart                         | A Coldstart is done on the beginning of each switch on time. A Coldstart can happen only, if the VBar Units is disconnected from power for more than 5 Seconds.  |
| ✔ | 0:00  | Reset Reason: Power On            | This happens if power is applied to the VBar unit. Usually this is ok, but it shall never happen in operational mode. So if a reset happens during flight, this points to a power problem. During flight the power on reset results in a warmstart. If a coldstart happens during flight, the power loss was more than 5 Seconds       |

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| ▶ | 0:00 | Bank 0 Loaded               | Bank 0 was loaded from the non volatile memory. This can be triggered my manual backswitch from the userinterface as well as in flight if bank switch is programmed to the aux channel. On Startup the Bank 0 is loaded by default.   |
| ▶ | 0:00 | Governor Mode Throttle      | Governor off, the servo moves with the throttle input channel   |
| ▶ | 0:06 | Calibration Finished        | At each Coldstart, the sensor and RC Values are calibrated to the actual seen values. If the calibration is finished, this message confirms the storage of data into the internal non volatile calibration memory   |
| ✔ | 0:16 | Good Health Message (10sec) | This Message describes the good health state. That means, that the VBar unit does not see any error or Info Message in the last 10 Seconds.   |
| ✔ | 0:26 | Good Health Message (10sec) | This Message describes the good health state. That means, that the VBar unit does not see any error or Info Message in the last 10 Seconds.   |
| ✔ | 0:36 | Good Health Message (10sec) | This Message describes the good health state. That means, that the VBar unit does not see any error or Info Message in the last 10 Seconds.   |
| ✔ | 0:46 | Good Health Message (10sec) | This Message describes the good health state. That means, that the VBar unit does not see any error or Info Message in the last 10 Seconds.   |
| ✔ | 0:56 | Good Health Message (10sec) | This Message describes the good health state. That means, that the VBar unit does not see any error or Info Message in the last 10 Seconds.   |
| ✔ | 1:06 | Good Health Message (10sec) | This Message describes the good health state. That means, that the VBar unit does not see any error or Info Message in the last 10 Seconds.   |
| ✔ | 1:16 | Good Health Message (10sec) | This Message describes the good health state. That means, that the VBar unit does not see any error or Info Message in the last 10 Seconds.   |
| ✔ | 1:26 | Good Health Message (10sec) | This Message describes the good health state. That means, that the VBar unit does not see any error or Info Message in the last 10 Seconds.   |
| ▶ | 1:29 | Governor ON                 | Governor switched to mode ON  |
| ✔ | 1:39 | Good Health Message (10sec) | This Message describes the good health state. That means, that the VBar unit does not see any error or Info Message in the last 10 Seconds.   |
| ▶ | 1:41 | Governor Mode Throttle      | Governor off, the servo moves with the throttle input channel   |
| ▶ | 1:44 | Governor ON                 | Governor switched to mode ON  |
| ▶ | 1:47 | Governor Mode Throttle      | Governor off, the servo moves with the throttle input channel   |
| ▶ | 1:48 | Governor ON                 | Governor switched to mode ON  |
| ▶ | 1:48 | Governor Mode Throttle      | Governor off, the servo moves with the throttle input channel   |
| ▶ | 1:49 | Governor ON                 | Governor switched to mode ON  |
| ▶ | 1:49 | Governor Mode Throttle      | Governor off, the servo moves with the throttle input channel   |
| ▶ | 1:56 | Governor Mode Throttle      | Governor off, the servo moves with the throttle input channel   |
| ✔ | 2:06 | Good Health Message (10sec) | This Message describes the good health state. That means, that the VBar unit does not see any error or Info Message in the last 10 Seconds.   |
| ▶ | 2:13 | Testmode Started            | The testmode ist entered intentionally by the user with the command on a Controlpanel or any other control terminal. The Entering command is checksum tested, so it cannot happen accidentally. In Testmode the normal control loop algorithm is not running, so its important to leave the Testmode prior flight. Its only can happen to fly in testmode with bluetooth. |
| ▶ | 2:16 | Testmode Started            | The testmode ist entered intentionally by the user with the command on a Controlpanel or any other control terminal. The Entering command is checksum tested, so it cannot happen accidentally. In Testmode the normal control loop algorithm is not running, so its important to leave the Testmode prior flight. Its only can happen to fly in testmode with bluetooth. |
| ▶ | 2:18 | Testmode Started            | The testmode ist entered intentionally by the user with the command on a Controlpanel or any other control terminal. The Entering command is checksum tested, so it cannot happen accidentally. In Testmode the normal control loop algorithm is not running, so its important to leave the Testmode prior flight. Its only can happen to fly in testmode with bluetooth. |
| ▶ | 2:20 | Testmode Started            | The testmode ist entered intentionally by the user with the command on a Controlpanel or any other control terminal. The Entering command is checksum tested, so it cannot happen accidentally. In Testmode the normal control loop algorithm is not running, so its important to leave the Testmode prior flight. Its only can happen to fly in testmode with bluetooth. |
| ▶ | 2:22 | Testmode Started            | The testmode ist entered intentionally by the user with the command on a Controlpanel or any other control terminal. The Entering command is checksum tested, so it cannot happen accidentally. In Testmode the normal control loop algorithm is not running, so its important to leave the Testmode prior flight. Its only can happen to fly in testmode with bluetooth. |
| ▶ | 2:24 | Testmode Started            | The testmode ist entered intentionally by the user with the command on a Controlpanel or any other control terminal. The Entering command is checksum tested, so it cannot happen accidentally. In Testmode the normal control loop algorithm is not running, so its important to leave the Testmode prior flight. Its only can happen to fly in testmode with bluetooth. |

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| ▶ | 2:26 | Testmode Started               | The testmode ist entered intentionally by the user with the command on a Controlpanel or any other control terminal. The Entering command is checksum tested, so it cannot happen accidentally. In Testmode the normal control loop algorithm is not running, so its important to leave the Testmode prior flight. Its only can happen to fly in testmode with bluetooth. |
| ▶ | 2:27 | Testmode Started               | The testmode ist entered intentionally by the user with the command on a Controlpanel or any other control terminal. The Entering command is checksum tested, so it cannot happen accidentally. In Testmode the normal control loop algorithm is not running, so its important to leave the Testmode prior flight. Its only can happen to fly in testmode with bluetooth. |
| ▶ | 2:33 | Testmode Started               | The testmode ist entered intentionally by the user with the command on a Controlpanel or any other control terminal. The Entering command is checksum tested, so it cannot happen accidentally. In Testmode the normal control loop algorithm is not running, so its important to leave the Testmode prior flight. Its only can happen to fly in testmode with bluetooth. |
| ▶ | 2:40 | Testmode Started               | The testmode ist entered intentionally by the user with the command on a Controlpanel or any other control terminal. The Entering command is checksum tested, so it cannot happen accidentally. In Testmode the normal control loop algorithm is not running, so its important to leave the Testmode prior flight. Its only can happen to fly in testmode with bluetooth. |
| ▶ | 2:45 | Testmode Started               | The testmode ist entered intentionally by the user with the command on a Controlpanel or any other control terminal. The Entering command is checksum tested, so it cannot happen accidentally. In Testmode the normal control loop algorithm is not running, so its important to leave the Testmode prior flight. Its only can happen to fly in testmode with bluetooth. |
| ✔ | 2:55 | Good Health Message (10sec)    | This Message describes the good health state. That means, that the VBar unit does not see any error or Info Message in the last 10 Seconds.   |
| ▶ | 3:00 | Testmode Started               | The testmode ist entered intentionally by the user with the command on a Controlpanel or any other control terminal. The Entering command is checksum tested, so it cannot happen accidentally. In Testmode the normal control loop algorithm is not running, so its important to leave the Testmode prior flight. Its only can happen to fly in testmode with bluetooth. |
| ▶ | 3:04 | Testmode Started               | The testmode ist entered intentionally by the user with the command on a Controlpanel or any other control terminal. The Entering command is checksum tested, so it cannot happen accidentally. In Testmode the normal control loop algorithm is not running, so its important to leave the Testmode prior flight. Its only can happen to fly in testmode with bluetooth. |
| ▶ | 3:14 | Governor ON                    | Governor switched to mode ON  |
| ✔ | 3:24 | Good Health Message (10sec)    | This Message describes the good health state. That means, that the VBar unit does not see any error or Info Message in the last 10 Seconds.   |
| ✔ | 3:34 | Good Health Message (10sec)    | This Message describes the good health state. That means, that the VBar unit does not see any error or Info Message in the last 10 Seconds.   |
| ✔ | 3:44 | Good Health Message (10sec)    | This Message describes the good health state. That means, that the VBar unit does not see any error or Info Message in the last 10 Seconds.   |
| ✔ | 3:54 | Good Health Message (10sec)    | This Message describes the good health state. That means, that the VBar unit does not see any error or Info Message in the last 10 Seconds.   |
| ✔ | 4:04 | Good Health Message (10sec)    | This Message describes the good health state. That means, that the VBar unit does not see any error or Info Message in the last 10 Seconds.   |
| ✔ | 4:14 | Good Health Message (10sec)    | This Message describes the good health state. That means, that the VBar unit does not see any error or Info Message in the last 10 Seconds.   |
| ▶ | 4:15 | Governor Sensor no Signal      | The Sensor does not deliver a usable Signal. This happens if the Rotor does not move, or if the Sensor fails during flight.   |
|   | 4:15 | Governor Sensor Signal Failure | The Sensor delivers a Signals that has too high frequency. This usually points to a defect of the wire or noise that is coupled into the sensor wire.   |
| ▶ | 4:16 | Governor Sensor no Signal      | The Sensor does not deliver a usable Signal. This happens if the Rotor does not move, or if the Sensor fails during flight.   |
| ✔ | 4:26 | Good Health Message (10sec)    | This Message describes the good health state. That means, that the VBar unit does not see any error or Info Message in the last 10 Seconds.   |
| ▶ | 4:32 | Governor Sensor no Signal      | The Sensor does not deliver a usable Signal. This happens if the Rotor does not move, or if the Sensor fails during flight.   |
|   | 4:32 | Governor Sensor Signal Failure | The Sensor delivers a Signals that has too high frequency. This usually points to a defect of the wire or noise that is coupled into the sensor wire.   |
| ✔ | 4:42 | Good Health Message (10sec)    | This Message describes the good health state. That means, that the VBar unit does not see any error or Info Message in the last 10 Seconds.   |
| ✔ | 4:52 | Good Health Message (10sec)    | This Message describes the good health state. That means, that the VBar unit does not see any error or Info Message in the last 10 Seconds.   |
| ✔ | 5:02 | Good Health Message (10sec)    | This Message describes the good health state. That means, that the VBar unit does not see any error or Info Message in the last 10 Seconds.   |
| ✔ | 5:12 | Good Health Message (10sec)    | This Message describes the good health state. That means, that the VBar unit does not see any error or Info Message in the last 10 Seconds.   |
| ✔ | 5:22 | Good Health Message (10sec)    | This Message describes the good health state. That means, that the VBar unit does not see any error or Info Message in the last 10 Seconds.   |

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| ▶ | 5:27 | Governor Sensor no Signal      | The Sensor does not deliver a usable Signal. This happens if the Rotor does not move, or if the Sensor fails during flight.   |
|   | 5:27 | Governor Sensor Signal Failure | The Sensor delivers a Signals that has too high frequency. This usually points to a defect of the wire or noise that is coupled into the sensor wire.   |
| ▶ | 5:28 | Governor Sensor no Signal      | The Sensor does not deliver a usable Signal. This happens if the Rotor does not move, or if the Sensor fails during flight.   |
| ▶ | 5:35 | Governor Sensor no Signal      | The Sensor does not deliver a usable Signal. This happens if the Rotor does not move, or if the Sensor fails during flight.   |
|   | 5:35 | Governor Sensor Signal Failure | The Sensor delivers a Signals that has too high frequency. This usually points to a defect of the wire or noise that is coupled into the sensor wire.   |
| ▶ | 5:36 | Governor Sensor no Signal      | The Sensor does not deliver a usable Signal. This happens if the Rotor does not move, or if the Sensor fails during flight.   |
| ▶ | 5:37 | Governor Sensor no Signal      | The Sensor does not deliver a usable Signal. This happens if the Rotor does not move, or if the Sensor fails during flight.   |
| ✔ | 5:47 | Good Health Message (10sec)    | This Message describes the good health state. That means, that the VBar unit does not see any error or Info Message in the last 10 Seconds.   |
| ✔ | 5:57 | Good Health Message (10sec)    | This Message describes the good health state. That means, that the VBar unit does not see any error or Info Message in the last 10 Seconds.   |
| ▶ | 6:07 | Governor Sensor no Signal      | The Sensor does not deliver a usable Signal. This happens if the Rotor does not move, or if the Sensor fails during flight.   |
| ▶ | 6:08 | Governor Sensor no Signal      | The Sensor does not deliver a usable Signal. This happens if the Rotor does not move, or if the Sensor fails during flight.   |
| ✔ | 6:18 | Good Health Message (10sec)    | This Message describes the good health state. That means, that the VBar unit does not see any error or Info Message in the last 10 Seconds.   |
| ▶ | 6:25 | Governor Sensor no Signal      | The Sensor does not deliver a usable Signal. This happens if the Rotor does not move, or if the Sensor fails during flight.   |
| ▶ | 6:26 | Governor Sensor no Signal      | The Sensor does not deliver a usable Signal. This happens if the Rotor does not move, or if the Sensor fails during flight.   |
| ▶ | 6:36 | Governor Sensor no Signal      | The Sensor does not deliver a usable Signal. This happens if the Rotor does not move, or if the Sensor fails during flight.   |
| ▶ | 6:37 | Governor Sensor no Signal      | The Sensor does not deliver a usable Signal. This happens if the Rotor does not move, or if the Sensor fails during flight.   |
| ▶ | 6:38 | Governor Sensor no Signal      | The Sensor does not deliver a usable Signal. This happens if the Rotor does not move, or if the Sensor fails during flight.   |
| ▶ | 6:39 | Governor Sensor no Signal      | The Sensor does not deliver a usable Signal. This happens if the Rotor does not move, or if the Sensor fails during flight.   |
| ✔ | 6:49 | Good Health Message (10sec)    | This Message describes the good health state. That means, that the VBar unit does not see any error or Info Message in the last 10 Seconds.   |
| ✔ | 6:59 | Good Health Message (10sec)    | This Message describes the good health state. That means, that the VBar unit does not see any error or Info Message in the last 10 Seconds.   |
| ✔ | 7:09 | Good Health Message (10sec)    | This Message describes the good health state. That means, that the VBar unit does not see any error or Info Message in the last 10 Seconds.   |
| ✔ | 7:19 | Good Health Message (10sec)    | This Message describes the good health state. That means, that the VBar unit does not see any error or Info Message in the last 10 Seconds.   |
| ✔ | 7:29 | Good Health Message (10sec)    | This Message describes the good health state. That means, that the VBar unit does not see any error or Info Message in the last 10 Seconds.   |
| ✔ | 7:39 | Good Health Message (10sec)    | This Message describes the good health state. That means, that the VBar unit does not see any error or Info Message in the last 10 Seconds.   |
| ▶ | 7:47 | Testmode Started               | The testmode ist entered intentionally by the user with the command on a Controlpanel or any other control terminal. The Entering command is checksum tested, so it cannot happen accidentally. In Testmode the normal control loop algorithm is not running, so its important to leave the Testmode prior flight. Its only can happen to fly in testmode with bluetooth. |
| ✔ | 7:57 | Good Health Message (10sec)    | This Message describes the good health state. That means, that the VBar unit does not see any error or Info Message in the last 10 Seconds.   |
| ✔ | 8:07 | Good Health Message (10sec)    | This Message describes the good health state. That means, that the VBar unit does not see any error or Info Message in the last 10 Seconds.   |

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| ▶ | 8:12   | Testmode Started               | The testmode ist entered intentionally by the user with the command on a Controlpanel or any other control terminal. The Entering command is checksum tested, so it cannot happen accidentally. In Testmode the normal control loop algorithm is not running, so its important to leave the Testmode prior flight. Its only can happen to fly in testmode with bluetooth. |
| ▶ | 8:20   | Testmode Started               | The testmode ist entered intentionally by the user with the command on a Controlpanel or any other control terminal. The Entering command is checksum tested, so it cannot happen accidentally. In Testmode the normal control loop algorithm is not running, so its important to leave the Testmode prior flight. Its only can happen to fly in testmode with bluetooth. |
| ▶ | 8:24   | Testmode Started               | The testmode ist entered intentionally by the user with the command on a Controlpanel or any other control terminal. The Entering command is checksum tested, so it cannot happen accidentally. In Testmode the normal control loop algorithm is not running, so its important to leave the Testmode prior flight. Its only can happen to fly in testmode with bluetooth. |
| ▶ | 8:28   | Testmode Started               | The testmode ist entered intentionally by the user with the command on a Controlpanel or any other control terminal. The Entering command is checksum tested, so it cannot happen accidentally. In Testmode the normal control loop algorithm is not running, so its important to leave the Testmode prior flight. Its only can happen to fly in testmode with bluetooth. |
| ▶ | 8:30   | Testmode Started               | The testmode ist entered intentionally by the user with the command on a Controlpanel or any other control terminal. The Entering command is checksum tested, so it cannot happen accidentally. In Testmode the normal control loop algorithm is not running, so its important to leave the Testmode prior flight. Its only can happen to fly in testmode with bluetooth. |
| ▶ | 8:33   | Testmode Started               | The testmode ist entered intentionally by the user with the command on a Controlpanel or any other control terminal. The Entering command is checksum tested, so it cannot happen accidentally. In Testmode the normal control loop algorithm is not running, so its important to leave the Testmode prior flight. Its only can happen to fly in testmode with bluetooth. |
| ▶ | 8:38   | Testmode Ended                 | Testmode has been switched off intentially. Normal control loop is in action now  |
| ✔ | 8:48   | Good Health Message (10sec)    | This Message describes the good health state. That means, that the VBar unit does not see any error or Info Message in the last 10 Seconds.   |
| ✔ | 8:58   | Good Health Message (10sec)    | This Message describes the good health state. That means, that the VBar unit does not see any error or Info Message in the last 10 Seconds.   |
| ✔ | 9:08   | Good Health Message (10sec)    | This Message describes the good health state. That means, that the VBar unit does not see any error or Info Message in the last 10 Seconds.   |
| ✔ | 9:18   | Good Health Message (10sec)    | This Message describes the good health state. That means, that the VBar unit does not see any error or Info Message in the last 10 Seconds.   |
| ✔ | 9:28   | Good Health Message (10sec)    | This Message describes the good health state. That means, that the VBar unit does not see any error or Info Message in the last 10 Seconds.   |
| ▶ | 9:38   | Testmode Started               | The testmode ist entered intentionally by the user with the command on a Controlpanel or any other control terminal. The Entering command is checksum tested, so it cannot happen accidentally. In Testmode the normal control loop algorithm is not running, so its important to leave the Testmode prior flight. Its only can happen to fly in testmode with bluetooth. |
| ▶ | 9:40   | Testmode Started               | The testmode ist entered intentionally by the user with the command on a Controlpanel or any other control terminal. The Entering command is checksum tested, so it cannot happen accidentally. In Testmode the normal control loop algorithm is not running, so its important to leave the Testmode prior flight. Its only can happen to fly in testmode with bluetooth. |
| ▶ | 9:43   | Testmode Started               | The testmode ist entered intentionally by the user with the command on a Controlpanel or any other control terminal. The Entering command is checksum tested, so it cannot happen accidentally. In Testmode the normal control loop algorithm is not running, so its important to leave the Testmode prior flight. Its only can happen to fly in testmode with bluetooth. |
| ▶ | 9:49   | Testmode Started               | The testmode ist entered intentionally by the user with the command on a Controlpanel or any other control terminal. The Entering command is checksum tested, so it cannot happen accidentally. In Testmode the normal control loop algorithm is not running, so its important to leave the Testmode prior flight. Its only can happen to fly in testmode with bluetooth. |
| ✔ | 9:59   | Good Health Message (10sec)    | This Message describes the good health state. That means, that the VBar unit does not see any error or Info Message in the last 10 Seconds.   |
| ▶ | 10:02  | Governor Sensor no Signal      | The Sensor does not deliver a usable Signal. This happens if the Rotor does not move, or if the Sensor fails during flight.   |
|   | 10:02  | Governor Sensor Signal Failure | The Sensor delivers a Signals that has too high frequency. This usually points to a defect of the wire or noise that is coupled into the sensor wire.   |
| ▶ | 10:04  | Governor Sensor no Signal      | The Sensor does not deliver a usable Signal. This happens if the Rotor does not move, or if the Sensor fails during flight.   |
| ▶ | 10:03  | Governor Sensor no Signal      | The Sensor does not deliver a usable Signal. This happens if the Rotor does not move, or if the Sensor fails during flight.   |
| ▶ | 10:04  | Governor Sensor no Signal      | The Sensor does not deliver a usable Signal. This happens if the Rotor does not move, or if the Sensor fails during flight.   |
| ▶ | 10:05  | Governor Sensor no Signal      | The Sensor does not deliver a usable Signal. This happens if the Rotor does not move, or if the Sensor fails during flight.   |
| ✔ | 10:025 | Good Health Message (10sec)    | This Message describes the good health state. That means, that the VBar unit does not see any error or Info Message in the last 10 Seconds.   |
| ✔ | 10:035 | Good Health Message (10sec)    | This Message describes the good health state. That means, that the VBar unit does not see any error or Info Message in the last 10 Seconds.   |

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| ✔ | 10:4<br>5 | Good Health Message (10sec) | This Message describes the good health state. That means, that the VBar unit does not see any error or Info Message in the last 10 Seconds.   |
| ▶ | 10:5<br>2 | Testmode Started            | The testmode ist entered intentionally by the user with the command on a Controlpanel or any other control terminal. The Entering command is checksum tested, so it cannot happen accidentally. In Testmode the normal control loop algorithm is not running, so its important to leave the Testmode prior flight. Its only can happen to fly in testmode with bluetooth. |
| ▶ | 10:5<br>6 | Testmode Started            | The testmode ist entered intentionally by the user with the command on a Controlpanel or any other control terminal. The Entering command is checksum tested, so it cannot happen accidentally. In Testmode the normal control loop algorithm is not running, so its important to leave the Testmode prior flight. Its only can happen to fly in testmode with bluetooth. |
| ▶ | 10:5<br>7 | Testmode Started            | The testmode ist entered intentionally by the user with the command on a Controlpanel or any other control terminal. The Entering command is checksum tested, so it cannot happen accidentally. In Testmode the normal control loop algorithm is not running, so its important to leave the Testmode prior flight. Its only can happen to fly in testmode with bluetooth. |
| ▶ | 10:5<br>9 | Testmode Started            | The testmode ist entered intentionally by the user with the command on a Controlpanel or any other control terminal. The Entering command is checksum tested, so it cannot happen accidentally. In Testmode the normal control loop algorithm is not running, so its important to leave the Testmode prior flight. Its only can happen to fly in testmode with bluetooth. |
| ▶ | 11:0<br>0 | Testmode Started            | The testmode ist entered intentionally by the user with the command on a Controlpanel or any other control terminal. The Entering command is checksum tested, so it cannot happen accidentally. In Testmode the normal control loop algorithm is not running, so its important to leave the Testmode prior flight. Its only can happen to fly in testmode with bluetooth. |
| ▶ | 11:0<br>1 | Testmode Ended              | Testmode has been switched off intentionally. Normal control loop is in action now  |
| ✔ | 11:1<br>1 | Good Health Message (10sec) | This Message describes the good health state. That means, that the VBar unit does not see any error or Info Message in the last 10 Seconds.   |
| ✔ | 11:2<br>1 | Good Health Message (10sec) | This Message describes the good health state. That means, that the VBar unit does not see any error or Info Message in the last 10 Seconds.   |
| ▶ | 11:2<br>7 | Governor Mode Throttle      | Governor off, the servo moves with the throttle input channel   |
| ▶ | 11:3<br>1 | Governor ON                 | Governor switched to mode ON  |
| ✔ | 11:4<br>1 | Good Health Message (10sec) | This Message describes the good health state. That means, that the VBar unit does not see any error or Info Message in the last 10 Seconds.   |
| ✔ | 11:5<br>1 | Good Health Message (10sec) | This Message describes the good health state. That means, that the VBar unit does not see any error or Info Message in the last 10 Seconds.   |
| ▶ | 11:5<br>4 | Governor Mode Throttle      | Governor off, the servo moves with the throttle input channel   |
| ✔ | 12:0<br>4 | Good Health Message (10sec) | This Message describes the good health state. That means, that the VBar unit does not see any error or Info Message in the last 10 Seconds.   |
| ✔ | 0:00      | Coldstart                   | A Coldstart is done on the beginning of each switch on time. A Coldstart can happen only, if the VBar Units is disconnected from power for more than 5 Seconds.   |
| ✔ | 0:00      | Reset Reason: Power On      | This happens if power is applied to the VBar unit. Usually this is ok, but it shall never happen in operational mode. So if a reset happens during flight, this points to a power problem. During flight the power on reset results in a warmstart. If a coldstart happens during flight, the power loss was more than 5 Seconds  |
| ▶ | 0:00      | Bank 0 Loaded               | Bank 0 was loaded from the non volatile memory. This can be triggered my manual backswitch from the userinterface as well as in flight if bank switch is programmed to the aux channel. On Startup the Bank 0 is loaded by default.   |
| ▶ | 0:00      | Governor Mode Throttle      | Governor off, the servo moves with the throttle input channel   |
| ▶ | 0:07      | Calibration Finished        | At each Coldstart, the sensor and RC Values are calibrated to the actual seen values. If the calibration is finished, this message confirms the storage of data into the internal non volatile calibration memory   |
| ▶ | 0:16      | Governor ON                 | Governor switched to mode ON  |
| ▶ | 0:16      | Governor Mode Throttle      | Governor off, the servo moves with the throttle input channel   |
| ▶ | 0:17      | Governor Mode Throttle      | Governor off, the servo moves with the throttle input channel   |
| ✔ | 0:27      | Good Health Message (10sec) | This Message describes the good health state. That means, that the VBar unit does not see any error or Info Message in the last 10 Seconds.   |
| ▶ | 0:33      | Testmode Started            | The testmode ist entered intentionally by the user with the command on a Controlpanel or any other control terminal. The Entering command is checksum tested, so it cannot happen accidentally. In Testmode the normal control loop algorithm is not running, so its important to leave the Testmode prior flight. Its only can happen to fly in testmode with bluetooth. |
| ▶ | 0:35      | Testmode Started            | The testmode ist entered intentionally by the user with the command on a Controlpanel or any other control terminal. The Entering command is checksum tested, so it cannot happen accidentally. In Testmode the normal control loop algorithm is not running, so its important to leave the Testmode prior flight. Its only can happen to fly in testmode with bluetooth. |

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| ▶ | 0:38 | Testmode Started               | The testmode ist entered intentionally by the user with the command on a Controlpanel or any other control terminal. The Entering command is checksum tested, so it cannot happen accidentally. In Testmode the normal control loop algorithm is not running, so its important to leave the Testmode prior flight. Its only can happen to fly in testmode with bluetooth. |
| ✔ | 0:48 | Good Health Message (10sec)    | This Message describes the good health state. That means, that the VBar unit does not see any error or Info Message in the last 10 Seconds.   |
| ✔ | 0:58 | Good Health Message (10sec)    | This Message describes the good health state. That means, that the VBar unit does not see any error or Info Message in the last 10 Seconds.   |
| ✔ | 1:08 | Good Health Message (10sec)    | This Message describes the good health state. That means, that the VBar unit does not see any error or Info Message in the last 10 Seconds.   |
| ✔ | 1:18 | Good Health Message (10sec)    | This Message describes the good health state. That means, that the VBar unit does not see any error or Info Message in the last 10 Seconds.   |
| ✔ | 1:28 | Good Health Message (10sec)    | This Message describes the good health state. That means, that the VBar unit does not see any error or Info Message in the last 10 Seconds.   |
| ✔ | 1:38 | Good Health Message (10sec)    | This Message describes the good health state. That means, that the VBar unit does not see any error or Info Message in the last 10 Seconds.   |
| ✔ | 1:48 | Good Health Message (10sec)    | This Message describes the good health state. That means, that the VBar unit does not see any error or Info Message in the last 10 Seconds.   |
| ▶ | 1:52 | Governor ON                    | Governor switched to mode ON  |
| ✔ | 2:02 | Good Health Message (10sec)    | This Message describes the good health state. That means, that the VBar unit does not see any error or Info Message in the last 10 Seconds.   |
| ✔ | 2:12 | Good Health Message (10sec)    | This Message describes the good health state. That means, that the VBar unit does not see any error or Info Message in the last 10 Seconds.   |
| ▶ | 2:15 | Governor Sensor no Signal      | The Sensor does not deliver a usable Signal. This happens if the Rotor does not move, or if the Sensor fails during flight.   |
|   | 2:15 | Governor Sensor Signal Failure | The Sensor delivers a Signals that has too high frequency. This usually points to a defect of the wire or noise that is coupled into the sensor wire.   |
| ▶ | 2:16 | Governor Sensor no Signal      | The Sensor does not deliver a usable Signal. This happens if the Rotor does not move, or if the Sensor fails during flight.   |
| ✔ | 2:26 | Good Health Message (10sec)    | This Message describes the good health state. That means, that the VBar unit does not see any error or Info Message in the last 10 Seconds.   |
| ✔ | 2:36 | Good Health Message (10sec)    | This Message describes the good health state. That means, that the VBar unit does not see any error or Info Message in the last 10 Seconds.   |
| ✔ | 2:46 | Good Health Message (10sec)    | This Message describes the good health state. That means, that the VBar unit does not see any error or Info Message in the last 10 Seconds.   |
| ✔ | 2:56 | Good Health Message (10sec)    | This Message describes the good health state. That means, that the VBar unit does not see any error or Info Message in the last 10 Seconds.   |
| ✔ | 3:06 | Good Health Message (10sec)    | This Message describes the good health state. That means, that the VBar unit does not see any error or Info Message in the last 10 Seconds.   |
| ✔ | 3:16 | Good Health Message (10sec)    | This Message describes the good health state. That means, that the VBar unit does not see any error or Info Message in the last 10 Seconds.   |
| ✔ | 3:26 | Good Health Message (10sec)    | This Message describes the good health state. That means, that the VBar unit does not see any error or Info Message in the last 10 Seconds.   |
| ▶ | 3:30 | Governor Sensor no Signal      | The Sensor does not deliver a usable Signal. This happens if the Rotor does not move, or if the Sensor fails during flight.   |
| ▶ | 3:31 | Governor Sensor no Signal      | The Sensor does not deliver a usable Signal. This happens if the Rotor does not move, or if the Sensor fails during flight.   |
| ▶ | 3:36 | Governor Sensor no Signal      | The Sensor does not deliver a usable Signal. This happens if the Rotor does not move, or if the Sensor fails during flight.   |
| ▶ | 3:37 | Governor Sensor no Signal      | The Sensor does not deliver a usable Signal. This happens if the Rotor does not move, or if the Sensor fails during flight.   |
| ▶ | 3:38 | Governor Sensor no Signal      | The Sensor does not deliver a usable Signal. This happens if the Rotor does not move, or if the Sensor fails during flight.   |
| ▶ | 3:39 | Governor Sensor no Signal      | The Sensor does not deliver a usable Signal. This happens if the Rotor does not move, or if the Sensor fails during flight.   |
| ▶ | 3:41 | Governor Sensor no Signal      | The Sensor does not deliver a usable Signal. This happens if the Rotor does not move, or if the Sensor fails during flight.   |

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| ▶ | 3:45 | Governor Sensor no Signal   | The Sensor does not deliver a usable Signal. This happens if the Rotor does not move, or if the Sensor fails during flight.   |
| ▶ | 3:46 | Governor Sensor no Signal   | The Sensor does not deliver a usable Signal. This happens if the Rotor does not move, or if the Sensor fails during flight.   |
| ▶ | 3:47 | Governor Sensor no Signal   | The Sensor does not deliver a usable Signal. This happens if the Rotor does not move, or if the Sensor fails during flight.   |
| ✔ | 3:57 | Good Health Message (10sec) | This Message describes the good health state. That means, that the VBar unit does not see any error or Info Message in the last 10 Seconds.   |
| ▶ | 4:05 | Governor ON                 | Governor switched to mode ON  |
| ▶ | 4:05 | Governor Mode Throttle      | Governor off, the servo moves with the throttle input channel   |
| ▶ | 4:06 | Governor ON                 | Governor switched to mode ON  |
| ▶ | 4:06 | Governor Mode Throttle      | Governor off, the servo moves with the throttle input channel   |
| ✔ | 4:16 | Good Health Message (10sec) | This Message describes the good health state. That means, that the VBar unit does not see any error or Info Message in the last 10 Seconds.   |
| ✔ | 4:26 | Good Health Message (10sec) | This Message describes the good health state. That means, that the VBar unit does not see any error or Info Message in the last 10 Seconds.   |
| ✔ | 4:36 | Good Health Message (10sec) | This Message describes the good health state. That means, that the VBar unit does not see any error or Info Message in the last 10 Seconds.   |
| ✔ | 4:46 | Good Health Message (10sec) | This Message describes the good health state. That means, that the VBar unit does not see any error or Info Message in the last 10 Seconds.   |
| ✔ | 4:56 | Good Health Message (10sec) | This Message describes the good health state. That means, that the VBar unit does not see any error or Info Message in the last 10 Seconds.   |
| ✔ | 5:06 | Good Health Message (10sec) | This Message describes the good health state. That means, that the VBar unit does not see any error or Info Message in the last 10 Seconds.   |
| ▶ | 5:07 | Testmode Started            | The testmode ist entered intentionally by the user with the command on a Controlpanel or any other control terminal. The Entering command is checksum tested, so it cannot happen accidentally. In Testmode the normal control loop algorithm is not running, so its important to leave the Testmode prior flight. Its only can happen to fly in testmode with bluetooth. |
| ▶ | 5:15 | Governor Mode Throttle      | Governor off, the servo moves with the throttle input channel   |
| ▶ | 5:19 | Governor ON                 | Governor switched to mode ON  |
| ▶ | 5:29 | Governor Mode Throttle      | Governor off, the servo moves with the throttle input channel   |
| ✔ | 5:39 | Good Health Message (10sec) | This Message describes the good health state. That means, that the VBar unit does not see any error or Info Message in the last 10 Seconds.   |
| ▶ | 5:49 | Governor ON                 | Governor switched to mode ON  |
| ▶ | 5:55 | Governor Mode Throttle      | Governor off, the servo moves with the throttle input channel   |
| ✔ | 6:05 | Good Health Message (10sec) | This Message describes the good health state. That means, that the VBar unit does not see any error or Info Message in the last 10 Seconds.   |
| ▶ | 6:06 | Testmode Started            | The testmode ist entered intentionally by the user with the command on a Controlpanel or any other control terminal. The Entering command is checksum tested, so it cannot happen accidentally. In Testmode the normal control loop algorithm is not running, so its important to leave the Testmode prior flight. Its only can happen to fly in testmode with bluetooth. |
| ▶ | 6:13 | Governor ON                 | Governor switched to mode ON  |
| ✔ | 6:23 | Good Health Message (10sec) | This Message describes the good health state. That means, that the VBar unit does not see any error or Info Message in the last 10 Seconds.   |
| ▶ | 6:30 | Testmode Started            | The testmode ist entered intentionally by the user with the command on a Controlpanel or any other control terminal. The Entering command is checksum tested, so it cannot happen accidentally. In Testmode the normal control loop algorithm is not running, so its important to leave the Testmode prior flight. Its only can happen to fly in testmode with bluetooth. |
| ✔ | 6:40 | Good Health Message (10sec) | This Message describes the good health state. That means, that the VBar unit does not see any error or Info Message in the last 10 Seconds.   |
| ✔ | 6:50 | Good Health Message (10sec) | This Message describes the good health state. That means, that the VBar unit does not see any error or Info Message in the last 10 Seconds.   |

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| ▶ | 6:55 | Testmode Started            | The testmode ist entered intentionally by the user with the command on a Controlpanel or any other control terminal. The Entering command is checksum tested, so it cannot happen accidentally. In Testmode the normal control loop algorithm is not running, so its important to leave the Testmode prior flight. Its only can happen to fly in testmode with bluetooth. |
| ▶ | 7:03 | Testmode Started            | The testmode ist entered intentionally by the user with the command on a Controlpanel or any other control terminal. The Entering command is checksum tested, so it cannot happen accidentally. In Testmode the normal control loop algorithm is not running, so its important to leave the Testmode prior flight. Its only can happen to fly in testmode with bluetooth. |
| ▶ | 7:05 | Testmode Started            | The testmode ist entered intentionally by the user with the command on a Controlpanel or any other control terminal. The Entering command is checksum tested, so it cannot happen accidentally. In Testmode the normal control loop algorithm is not running, so its important to leave the Testmode prior flight. Its only can happen to fly in testmode with bluetooth. |
| ▶ | 7:06 | Testmode Started            | The testmode ist entered intentionally by the user with the command on a Controlpanel or any other control terminal. The Entering command is checksum tested, so it cannot happen accidentally. In Testmode the normal control loop algorithm is not running, so its important to leave the Testmode prior flight. Its only can happen to fly in testmode with bluetooth. |
| ▶ | 7:10 | Testmode Ended              | Testmode has been switched off intentially. Normal control loop is in action now  |
| ▶ | 7:15 | Governor Mode Throttle      | Governor off, the servo moves with the throttle input channel   |
| ▶ | 7:19 | Governor ON                 | Governor switched to mode ON  |
| ✔ | 7:29 | Good Health Message (10sec) | This Message describes the good health state. That means, that the VBar unit does not see any error or Info Message in the last 10 Seconds.   |
| ✔ | 7:39 | Good Health Message (10sec) | This Message describes the good health state. That means, that the VBar unit does not see any error or Info Message in the last 10 Seconds.   |
| ▶ | 7:43 | Governor Mode Throttle      | Governor off, the servo moves with the throttle input channel   |
| ✔ | 7:53 | Good Health Message (10sec) | This Message describes the good health state. That means, that the VBar unit does not see any error or Info Message in the last 10 Seconds.   |
| ▶ | 7:56 | Governor ON                 | Governor switched to mode ON  |
| ✔ | 8:06 | Good Health Message (10sec) | This Message describes the good health state. That means, that the VBar unit does not see any error or Info Message in the last 10 Seconds.   |
| ▶ | 8:15 | Governor Mode Throttle      | Governor off, the servo moves with the throttle input channel   |
| ✔ | 8:25 | Good Health Message (10sec) | This Message describes the good health state. That means, that the VBar unit does not see any error or Info Message in the last 10 Seconds.   |
| ▶ | 8:31 | Governor ON                 | Governor switched to mode ON  |
| ▶ | 8:38 | Governor Mode Throttle      | Governor off, the servo moves with the throttle input channel   |
| ✔ | 8:48 | Good Health Message (10sec) | This Message describes the good health state. That means, that the VBar unit does not see any error or Info Message in the last 10 Seconds.   |
| ▶ | 8:54 | Governor ON                 | Governor switched to mode ON  |
| ✔ | 9:04 | Good Health Message (10sec) | This Message describes the good health state. That means, that the VBar unit does not see any error or Info Message in the last 10 Seconds.   |
| ▶ | 9:12 | Testmode Started            | The testmode ist entered intentionally by the user with the command on a Controlpanel or any other control terminal. The Entering command is checksum tested, so it cannot happen accidentally. In Testmode the normal control loop algorithm is not running, so its important to leave the Testmode prior flight. Its only can happen to fly in testmode with bluetooth. |
| ▶ | 9:17 | Testmode Started            | The testmode ist entered intentionally by the user with the command on a Controlpanel or any other control terminal. The Entering command is checksum tested, so it cannot happen accidentally. In Testmode the normal control loop algorithm is not running, so its important to leave the Testmode prior flight. Its only can happen to fly in testmode with bluetooth. |
| ▶ | 9:24 | Testmode Started            | The testmode ist entered intentionally by the user with the command on a Controlpanel or any other control terminal. The Entering command is checksum tested, so it cannot happen accidentally. In Testmode the normal control loop algorithm is not running, so its important to leave the Testmode prior flight. Its only can happen to fly in testmode with bluetooth. |
| ▶ | 9:29 | Governor Mode Throttle      | Governor off, the servo moves with the throttle input channel   |
| ▶ | 9:32 | Governor ON                 | Governor switched to mode ON  |
| ✔ | 9:42 | Good Health Message (10sec) | This Message describes the good health state. That means, that the VBar unit does not see any error or Info Message in the last 10 Seconds.   |
| ▶ | 9:45 | Testmode Started            | The testmode ist entered intentionally by the user with the command on a Controlpanel or any other control terminal. The Entering command is checksum tested, so it cannot happen accidentally. In Testmode the normal control loop algorithm is not running, so its important to leave the Testmode prior flight. Its only can happen to fly in testmode with bluetooth. |

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| ▶ | 9:52  | Testmode Started            | The testmode ist entered intentionally by the user with the command on a Controlpanel or any other control terminal. The Entering command is checksum tested, so it cannot happen accidentally. In Testmode the normal control loop algorithm is not running, so its important to leave the Testmode prior flight. Its only can happen to fly in testmode with bluetooth. |
| ▶ | 9:58  | Testmode Started            | The testmode ist entered intentionally by the user with the command on a Controlpanel or any other control terminal. The Entering command is checksum tested, so it cannot happen accidentally. In Testmode the normal control loop algorithm is not running, so its important to leave the Testmode prior flight. Its only can happen to fly in testmode with bluetooth. |
| ▶ | 9:59  | Testmode Started            | The testmode ist entered intentionally by the user with the command on a Controlpanel or any other control terminal. The Entering command is checksum tested, so it cannot happen accidentally. In Testmode the normal control loop algorithm is not running, so its important to leave the Testmode prior flight. Its only can happen to fly in testmode with bluetooth. |
| ▶ | 10:01 | Testmode Started            | The testmode ist entered intentionally by the user with the command on a Controlpanel or any other control terminal. The Entering command is checksum tested, so it cannot happen accidentally. In Testmode the normal control loop algorithm is not running, so its important to leave the Testmode prior flight. Its only can happen to fly in testmode with bluetooth. |
| ▶ | 10:02 | Testmode Ended              | Testmode has been switched off intentionally. Normal control loop is in action now  |
| ✔ | 10:12 | Good Health Message (10sec) | This Message describes the good health state. That means, that the VBar unit does not see any error or Info Message in the last 10 Seconds.   |
| ▶ | 10:14 | Governor Mode Throttle      | Governor off, the servo moves with the throttle input channel   |
| ▶ | 10:16 | Governor ON                 | Governor switched to mode ON  |
| ▶ | 10:19 | Governor Mode Throttle      | Governor off, the servo moves with the throttle input channel   |
| ▶ | 10:27 | Governor ON                 | Governor switched to mode ON  |
| ▶ | 10:30 | Governor Mode Throttle      | Governor off, the servo moves with the throttle input channel   |
| ▶ | 10:33 | Governor ON                 | Governor switched to mode ON  |
| ▶ | 10:35 | Governor Mode Throttle      | Governor off, the servo moves with the throttle input channel   |
| ▶ | 10:36 | Governor ON                 | Governor switched to mode ON  |
| ▶ | 10:41 | Governor Mode Throttle      | Governor off, the servo moves with the throttle input channel   |
| ✔ | 10:51 | Good Health Message (10sec) | This Message describes the good health state. That means, that the VBar unit does not see any error or Info Message in the last 10 Seconds.   |
| ✔ | 11:01 | Good Health Message (10sec) | This Message describes the good health state. That means, that the VBar unit does not see any error or Info Message in the last 10 Seconds.   |
| ✔ | 0:00  | Coldstart                   | A Coldstart is done on the beginning of each switch on time. A Coldstart can happen only, if the VBar Units is disconnected from power for more than 5 Seconds.   |
| ✔ | 0:00  | Reset Reason: Power On      | This happens if power is applied to the VBar unit. Usually this is ok, but it shall never happen in operational mode. So if a reset happens during flight, this points to a power problem. During flight the power on reset results in a warmstart. If a coldstart happens during flight, the power loss was more than 5 Seconds  |
| ▶ | 0:00  | Bank 0 Loaded               | Bank 0 was loaded from the non volatile memory. This can be triggered my manual backswitch from the userinterface as well as in flight if bank switch is programmed to the aux channel. On Startup the Bank 0 is loaded by default.   |
| ▶ | 0:00  | Governor Mode Throttle      | Governor off, the servo moves with the throttle input channel   |
| ▶ | 0:06  | Calibration Finished        | At each Coldstart, the sensor and RC Values are calibrated to the actual seen values. If the calibration is finished, this message confirms the storage of data into the internal non volatile calibration memory   |
| ✔ | 0:16  | Good Health Message (10sec) | This Message describes the good health state. That means, that the VBar unit does not see any error or Info Message in the last 10 Seconds.   |
| ✔ | 0:26  | Good Health Message (10sec) | This Message describes the good health state. That means, that the VBar unit does not see any error or Info Message in the last 10 Seconds.   |
| ✔ | 0:36  | Good Health Message (10sec) | This Message describes the good health state. That means, that the VBar unit does not see any error or Info Message in the last 10 Seconds.   |
| ✔ | 0:46  | Good Health Message (10sec) | This Message describes the good health state. That means, that the VBar unit does not see any error or Info Message in the last 10 Seconds.   |
| ✔ | 0:56  | Good Health Message (10sec) | This Message describes the good health state. That means, that the VBar unit does not see any error or Info Message in the last 10 Seconds.   |

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| ✔ | 1:06 | Good Health Message (10sec)       | This Message describes the good health state. That means, that the VBar unit does not see any error or Info Message in the last 10 Seconds.   |
| ✔ | 0:00 | Coldstart                         | A Coldstart is done on the beginning of each switch on time. A Coldstart can happen only, if the VBar Units is disconnected from power for more than 5 Seconds.   |
| ✔ | 0:00 | Reset Reason: Power On            | This happens if power is applied to the VBar unit. Usually this is ok, but it shall never happen in operational mode. So if a reset happens during flight, this points to a power problem. During flight the power on reset results in a warmstart. If a coldstart happens during flight, the power loss was more than 5 Seconds      |
| ▶ | 0:00 | Bank 0 Loaded                     | Bank 0 was loaded from the non volatile memory. This can be triggered my manual backswitch from the userinterface as well as in flight if bank switch is programmed to the aux channel. On Startup the Bank 0 is loaded by default.   |
| ▶ | 0:00 | Governor Mode Throttle            | Governor off, the servo moves with the throttle input channel   |
| ▶ | 0:06 | Calibration Finished              | At each Coldstart, the sensor and RC Values are calibrated to the actual seen values. If the calibration is finished, this message confirms the storage of data into the internal non volatile calibration memory   |
| ✔ | 0:16 | Good Health Message (10sec)       | This Message describes the good health state. That means, that the VBar unit does not see any error or Info Message in the last 10 Seconds.   |
| ✔ | 0:26 | Good Health Message (10sec)       | This Message describes the good health state. That means, that the VBar unit does not see any error or Info Message in the last 10 Seconds.   |
| ✔ | 0:36 | Good Health Message (10sec)       | This Message describes the good health state. That means, that the VBar unit does not see any error or Info Message in the last 10 Seconds.   |
| ✔ | 0:46 | Good Health Message (10sec)       | This Message describes the good health state. That means, that the VBar unit does not see any error or Info Message in the last 10 Seconds.   |
| ✔ | 0:56 | Good Health Message (10sec)       | This Message describes the good health state. That means, that the VBar unit does not see any error or Info Message in the last 10 Seconds.   |
| ✔ | 1:06 | Good Health Message (10sec)       | This Message describes the good health state. That means, that the VBar unit does not see any error or Info Message in the last 10 Seconds.   |
| ✔ | 1:16 | Good Health Message (10sec)       | This Message describes the good health state. That means, that the VBar unit does not see any error or Info Message in the last 10 Seconds.   |
| ✔ | 1:26 | Good Health Message (10sec)       | This Message describes the good health state. That means, that the VBar unit does not see any error or Info Message in the last 10 Seconds.   |
| ✔ | 1:36 | Good Health Message (10sec)       | This Message describes the good health state. That means, that the VBar unit does not see any error or Info Message in the last 10 Seconds.   |
| ✔ | 1:46 | Good Health Message (10sec)       | This Message describes the good health state. That means, that the VBar unit does not see any error or Info Message in the last 10 Seconds.   |
| ✔ | 1:56 | Good Health Message (10sec)       | This Message describes the good health state. That means, that the VBar unit does not see any error or Info Message in the last 10 Seconds.   |
| ✔ | 2:06 | Good Health Message (10sec)       | This Message describes the good health state. That means, that the VBar unit does not see any error or Info Message in the last 10 Seconds.   |
| ✔ | 2:16 | Good Health Message (10sec)       | This Message describes the good health state. That means, that the VBar unit does not see any error or Info Message in the last 10 Seconds.   |
| ▶ | 2:24 | Raised Vibration Level            | There was detected a raised level of Vibration. Since the vibration detector has to decide which signal is vibration and chis is the intended measurement signal, this can happen sometimes on hard 3d moves. It shall not happen all the time. If this error is reported repeditly very often, check the heli for vibration sources. |
| ▶ | 2:25 | Governor ON                       | Governor switched to mode ON  |
| ▶ | 2:25 | Governor is at Low Throttle Limit | There is a defined low limit, that the Governor will not fall below. lth this Limit is reached, this Info Message is issued. The Message is issued once for each touch of the limit. If the limit is touched, it means that your headspeed will be higher than programmed.  |
| ▶ | 2:30 | Governor is at Low Throttle Limit | There is a defined low limit, that the Governor will not fall below. lth this Limit is reached, this Info Message is issued. The Message is issued once for each touch of the limit. If the limit is touched, it means that your headspeed will be higher than programmed.  |
| ▶ | 2:31 | Governor is at Low Throttle Limit | There is a defined low limit, that the Governor will not fall below. lth this Limit is reached, this Info Message is issued. The Message is issued once for each touch of the limit. If the limit is touched, it means that your headspeed will be higher than programmed.  |
| ▶ | 2:32 | Governor is at Low Throttle Limit | There is a defined low limit, that the Governor will not fall below. lth this Limit is reached, this Info Message is issued. The Message is issued once for each touch of the limit. If the limit is touched, it means that your headspeed will be higher than programmed.  |
| ▶ | 2:33 | Governor is at Low Throttle Limit | There is a defined low limit, that the Governor will not fall below. lth this Limit is reached, this Info Message is issued. The Message is issued once for each touch of the limit. If the limit is touched, it means that your headspeed will be higher than programmed.  |
| ▶ | 2:36 | Governor is at Low Throttle Limit | There is a defined low limit, that the Governor will not fall below. lth this Limit is reached, this Info Message is issued. The Message is issued once for each touch of the limit. If the limit is touched, it means that your headspeed will be higher than programmed.  |
| ▶ | 2:40 | Governor is at Low Throttle Limit | There is a defined low limit, that the Governor will not fall below. lth this Limit is reached, this Info Message is issued. The Message is issued once for each touch of the limit. If the limit is touched, it means that your headspeed will be higher than programmed.  |

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| ▶ | 2:43 | Raised Vibration Level            | There was detected a raised level of Vibration. Since the vibration detector has to decide which signal is vibration and this is the intended measurement signal, this can happen sometimes on hard 3d moves. It shall not happen all the time. If this error is reported repeatedly very often, check the heli for vibration sources. |
| ▲ | 2:53 | High Vibration Level              | The control loop suffers from a high vibration level, that starts to render the sensors blind. Save flying is possible, but the stability will be degraded. Additionally slow drifts that happen may be caused by vibrations.  |
| ▲ | 3:02 | High Vibration Level              | The control loop suffers from a high vibration level, that starts to render the sensors blind. Save flying is possible, but the stability will be degraded. Additionally slow drifts that happen may be caused by vibrations.  |
| ▲ | 3:12 | High Vibration Level              | The control loop suffers from a high vibration level, that starts to render the sensors blind. Save flying is possible, but the stability will be degraded. Additionally slow drifts that happen may be caused by vibrations.  |
| ▶ | 3:19 | Governor is at Low Throttle Limit | There is a defined low limit, that the Governor will not fall below. If this Limit is reached, this Info Message is issued. The Message is issued once for each touch of the limit. If the limit is touched, it means that your headspeed will be higher than programmed.  |
| ▲ | 3:21 | High Vibration Level              | The control loop suffers from a high vibration level, that starts to render the sensors blind. Save flying is possible, but the stability will be degraded. Additionally slow drifts that happen may be caused by vibrations.  |
| ▶ | 3:22 | Governor is at Low Throttle Limit | There is a defined low limit, that the Governor will not fall below. If this Limit is reached, this Info Message is issued. The Message is issued once for each touch of the limit. If the limit is touched, it means that your headspeed will be higher than programmed.  |
| ▶ | 3:27 | Governor is at Low Throttle Limit | There is a defined low limit, that the Governor will not fall below. If this Limit is reached, this Info Message is issued. The Message is issued once for each touch of the limit. If the limit is touched, it means that your headspeed will be higher than programmed.  |
| ▲ | 3:31 | High Vibration Level              | The control loop suffers from a high vibration level, that starts to render the sensors blind. Save flying is possible, but the stability will be degraded. Additionally slow drifts that happen may be caused by vibrations.  |
| ▶ | 3:41 | Raised Vibration Level            | There was detected a raised level of Vibration. Since the vibration detector has to decide which signal is vibration and this is the intended measurement signal, this can happen sometimes on hard 3d moves. It shall not happen all the time. If this error is reported repeatedly very often, check the heli for vibration sources. |
| ▲ | 3:50 | High Vibration Level              | The control loop suffers from a high vibration level, that starts to render the sensors blind. Save flying is possible, but the stability will be degraded. Additionally slow drifts that happen may be caused by vibrations.  |
| ▲ | 4:00 | High Vibration Level              | The control loop suffers from a high vibration level, that starts to render the sensors blind. Save flying is possible, but the stability will be degraded. Additionally slow drifts that happen may be caused by vibrations.  |
| ▲ | 4:10 | High Vibration Level              | The control loop suffers from a high vibration level, that starts to render the sensors blind. Save flying is possible, but the stability will be degraded. Additionally slow drifts that happen may be caused by vibrations.  |
| ▲ | 4:19 | High Vibration Level              | The control loop suffers from a high vibration level, that starts to render the sensors blind. Save flying is possible, but the stability will be degraded. Additionally slow drifts that happen may be caused by vibrations.  |
| ▶ | 4:29 | Raised Vibration Level            | There was detected a raised level of Vibration. Since the vibration detector has to decide which signal is vibration and this is the intended measurement signal, this can happen sometimes on hard 3d moves. It shall not happen all the time. If this error is reported repeatedly very often, check the heli for vibration sources. |
| ▶ | 4:38 | Raised Vibration Level            | There was detected a raised level of Vibration. Since the vibration detector has to decide which signal is vibration and this is the intended measurement signal, this can happen sometimes on hard 3d moves. It shall not happen all the time. If this error is reported repeatedly very often, check the heli for vibration sources. |
| ▲ | 4:48 | High Vibration Level              | The control loop suffers from a high vibration level, that starts to render the sensors blind. Save flying is possible, but the stability will be degraded. Additionally slow drifts that happen may be caused by vibrations.  |
| ▲ | 4:58 | High Vibration Level              | The control loop suffers from a high vibration level, that starts to render the sensors blind. Save flying is possible, but the stability will be degraded. Additionally slow drifts that happen may be caused by vibrations.  |
| ▲ | 5:07 | High Vibration Level              | The control loop suffers from a high vibration level, that starts to render the sensors blind. Save flying is possible, but the stability will be degraded. Additionally slow drifts that happen may be caused by vibrations.  |
| ▲ | 5:17 | High Vibration Level              | The control loop suffers from a high vibration level, that starts to render the sensors blind. Save flying is possible, but the stability will be degraded. Additionally slow drifts that happen may be caused by vibrations.  |
| ▶ | 5:25 | Governor is at Low Throttle Limit | There is a defined low limit, that the Governor will not fall below. If this Limit is reached, this Info Message is issued. The Message is issued once for each touch of the limit. If the limit is touched, it means that your headspeed will be higher than programmed.  |
| ▲ | 5:27 | High Vibration Level              | The control loop suffers from a high vibration level, that starts to render the sensors blind. Save flying is possible, but the stability will be degraded. Additionally slow drifts that happen may be caused by vibrations.  |
| ▲ | 5:36 | High Vibration Level              | The control loop suffers from a high vibration level, that starts to render the sensors blind. Save flying is possible, but the stability will be degraded. Additionally slow drifts that happen may be caused by vibrations.  |
| ▶ | 5:37 | Governor is at Low Throttle Limit | There is a defined low limit, that the Governor will not fall below. If this Limit is reached, this Info Message is issued. The Message is issued once for each touch of the limit. If the limit is touched, it means that your headspeed will be higher than programmed.  |
| ▶ | 5:39 | Governor is at Low Throttle Limit | There is a defined low limit, that the Governor will not fall below. If this Limit is reached, this Info Message is issued. The Message is issued once for each touch of the limit. If the limit is touched, it means that your headspeed will be higher than programmed.  |
| ▶ | 5:40 | Governor is at Low Throttle Limit | There is a defined low limit, that the Governor will not fall below. If this Limit is reached, this Info Message is issued. The Message is issued once for each touch of the limit. If the limit is touched, it means that your headspeed will be higher than programmed.  |

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| ▶ | 5:41 | Governor Mode Throttle            | Governor off, the servo moves with the throttle input channel   |
| ⚠ | 5:46 | High Vibration Level              | The control loop suffers from a high vibration level, that starts to render the sensors blind. Save flying is possible, but the stability will be degraded. Additionally slow drifts that happen may be caused by vibrations.   |
| ✔ | 5:56 | Good Health Message (10sec)       | This Message describes the good health state. That means, that the VBar unit does not see any error or Info Message in the last 10 Seconds.   |
| ✔ | 6:06 | Good Health Message (10sec)       | This Message describes the good health state. That means, that the VBar unit does not see any error or Info Message in the last 10 Seconds.   |
| ✔ | 6:16 | Good Health Message (10sec)       | This Message describes the good health state. That means, that the VBar unit does not see any error or Info Message in the last 10 Seconds.   |
| ✔ | 0:00 | Coldstart                         | A Coldstart is done on the beginning of each switch on time. A Coldstart can happen only, if the VBar Units is disconnected from power for more than 5 Seconds.   |
| ✔ | 0:00 | Reset Reason: Power On            | This happens if power is applied to the VBar unit. Usually this is ok, but it shall never happen in operational mode. So if a reset happens during flight, this points to a power problem. During flight the power on reset results in a warmstart. If a coldstart happens during flight, the power loss was more than 5 Seconds      |
| ▶ | 0:00 | Bank 0 Loaded                     | Bank 0 was loaded from the non volatile memory. This can be triggered my manual backswitch from the userinterface as well as in flight if bank switch is programmed to the aux channel. On Startup the Bank 0 is loaded by default.   |
| ▶ | 0:00 | Governor Mode Throttle            | Governor off, the servo moves with the throttle input channel   |
| ▶ | 0:06 | Calibration Finished              | At each Coldstart, the sensor and RC Values are calibrated to the actual seen values. If the calibration is finished, this message confirms the storage of data into the internal non volatile calibration memory   |
| ✔ | 0:16 | Good Health Message (10sec)       | This Message describes the good health state. That means, that the VBar unit does not see any error or Info Message in the last 10 Seconds.   |
| ✔ | 0:26 | Good Health Message (10sec)       | This Message describes the good health state. That means, that the VBar unit does not see any error or Info Message in the last 10 Seconds.   |
| ▶ | 0:28 | Raised Vibration Level            | There was detected a raised level of Vibration. Since the vibration detector has to decide which signal is vibration and chis is the intended measurement signal, this can happen sometimes on hard 3d moves. It shall not happen all the time. If this error is reported repeditly very often, check the heli for vibration sources. |
| ✔ | 0:38 | Good Health Message (10sec)       | This Message describes the good health state. That means, that the VBar unit does not see any error or Info Message in the last 10 Seconds.   |
| ✔ | 0:48 | Good Health Message (10sec)       | This Message describes the good health state. That means, that the VBar unit does not see any error or Info Message in the last 10 Seconds.   |
| ✔ | 0:58 | Good Health Message (10sec)       | This Message describes the good health state. That means, that the VBar unit does not see any error or Info Message in the last 10 Seconds.   |
| ✔ | 1:08 | Good Health Message (10sec)       | This Message describes the good health state. That means, that the VBar unit does not see any error or Info Message in the last 10 Seconds.   |
| ✔ | 1:18 | Good Health Message (10sec)       | This Message describes the good health state. That means, that the VBar unit does not see any error or Info Message in the last 10 Seconds.   |
| ✔ | 1:28 | Good Health Message (10sec)       | This Message describes the good health state. That means, that the VBar unit does not see any error or Info Message in the last 10 Seconds.   |
| ▶ | 1:35 | Governor ON                       | Governor switched to mode ON  |
| ▶ | 1:36 | Raised Vibration Level            | There was detected a raised level of Vibration. Since the vibration detector has to decide which signal is vibration and chis is the intended measurement signal, this can happen sometimes on hard 3d moves. It shall not happen all the time. If this error is reported repeditly very often, check the heli for vibration sources. |
| ▶ | 1:36 | Governor is at Low Throttle Limit | There is a defined low limit, that the Governor will not fall below. lth this Limit is reached, this Info Message is issued. The Message is issued once for each touch of the limit. If the limit is touched, it means that your headspeed will be higher than programmed.  |
| ▶ | 1:45 | Raised Vibration Level            | There was detected a raised level of Vibration. Since the vibration detector has to decide which signal is vibration and chis is the intended measurement signal, this can happen sometimes on hard 3d moves. It shall not happen all the time. If this error is reported repeditly very often, check the heli for vibration sources. |
| ▶ | 1:55 | Raised Vibration Level            | There was detected a raised level of Vibration. Since the vibration detector has to decide which signal is vibration and chis is the intended measurement signal, this can happen sometimes on hard 3d moves. It shall not happen all the time. If this error is reported repeditly very often, check the heli for vibration sources. |
| ⚠ | 2:05 | High Vibration Level              | The control loop suffers from a high vibration level, that starts to render the sensors blind. Save flying is possible, but the stability will be degraded. Additionally slow drifts that happen may be caused by vibrations.   |
| ⚠ | 2:14 | High Vibration Level              | The control loop suffers from a high vibration level, that starts to render the sensors blind. Save flying is possible, but the stability will be degraded. Additionally slow drifts that happen may be caused by vibrations.   |
| ⚠ | 2:24 | High Vibration Level              | The control loop suffers from a high vibration level, that starts to render the sensors blind. Save flying is possible, but the stability will be degraded. Additionally slow drifts that happen may be caused by vibrations.   |

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| ▶ | 2:33 | Raised Vibration Level            | There was detected a raised level of Vibration. Since the vibration detector has to decide which signal is vibration and this is the intended measurement signal, this can happen sometimes on hard 3d moves. It shall not happen all the time. If this error is reported repeatedly very often, check the heli for vibration sources. |
| ⚠ | 2:43 | High Vibration Level              | The control loop suffers from a high vibration level, that starts to render the sensors blind. Save flying is possible, but the stability will be degraded. Additionally slow drifts that happen may be caused by vibrations.  |
| ⚠ | 2:53 | High Vibration Level              | The control loop suffers from a high vibration level, that starts to render the sensors blind. Save flying is possible, but the stability will be degraded. Additionally slow drifts that happen may be caused by vibrations.  |
| ⚠ | 3:02 | High Vibration Level              | The control loop suffers from a high vibration level, that starts to render the sensors blind. Save flying is possible, but the stability will be degraded. Additionally slow drifts that happen may be caused by vibrations.  |
| ⚠ | 3:12 | High Vibration Level              | The control loop suffers from a high vibration level, that starts to render the sensors blind. Save flying is possible, but the stability will be degraded. Additionally slow drifts that happen may be caused by vibrations.  |
| ▶ | 3:21 | Raised Vibration Level            | There was detected a raised level of Vibration. Since the vibration detector has to decide which signal is vibration and this is the intended measurement signal, this can happen sometimes on hard 3d moves. It shall not happen all the time. If this error is reported repeatedly very often, check the heli for vibration sources. |
| ⚠ | 3:31 | High Vibration Level              | The control loop suffers from a high vibration level, that starts to render the sensors blind. Save flying is possible, but the stability will be degraded. Additionally slow drifts that happen may be caused by vibrations.  |
| ⚠ | 3:41 | High Vibration Level              | The control loop suffers from a high vibration level, that starts to render the sensors blind. Save flying is possible, but the stability will be degraded. Additionally slow drifts that happen may be caused by vibrations.  |
| ▶ | 3:44 | Governor is at Low Throttle Limit | There is a defined low limit, that the Governor will not fall below. If this Limit is reached, this Info Message is issued. The Message is issued once for each touch of the limit. If the limit is touched, it means that your headspeed will be higher than programmed.  |
| ▶ | 3:45 | Governor is at Low Throttle Limit | There is a defined low limit, that the Governor will not fall below. If this Limit is reached, this Info Message is issued. The Message is issued once for each touch of the limit. If the limit is touched, it means that your headspeed will be higher than programmed.  |
| ✖ | 3:50 | Extreme Vibration Level           | Vibrations are extreme. That means, that the measurement signal is much lower than the signal level of the vibrations. No usable flying is possible with this level. Everything has to be checked and extended tests are needed to isolate and eliminate the source of vibrations  |
| ▶ | 3:55 | Governor is at Low Throttle Limit | There is a defined low limit, that the Governor will not fall below. If this Limit is reached, this Info Message is issued. The Message is issued once for each touch of the limit. If the limit is touched, it means that your headspeed will be higher than programmed.  |
| ▶ | 3:57 | Governor is at Low Throttle Limit | There is a defined low limit, that the Governor will not fall below. If this Limit is reached, this Info Message is issued. The Message is issued once for each touch of the limit. If the limit is touched, it means that your headspeed will be higher than programmed.  |
| ▶ | 3:58 | Governor is at Low Throttle Limit | There is a defined low limit, that the Governor will not fall below. If this Limit is reached, this Info Message is issued. The Message is issued once for each touch of the limit. If the limit is touched, it means that your headspeed will be higher than programmed.  |
| ▶ | 3:59 | Governor is at Low Throttle Limit | There is a defined low limit, that the Governor will not fall below. If this Limit is reached, this Info Message is issued. The Message is issued once for each touch of the limit. If the limit is touched, it means that your headspeed will be higher than programmed.  |
| ⚠ | 4:00 | High Vibration Level              | The control loop suffers from a high vibration level, that starts to render the sensors blind. Save flying is possible, but the stability will be degraded. Additionally slow drifts that happen may be caused by vibrations.  |
| ▶ | 4:01 | Governor is at Low Throttle Limit | There is a defined low limit, that the Governor will not fall below. If this Limit is reached, this Info Message is issued. The Message is issued once for each touch of the limit. If the limit is touched, it means that your headspeed will be higher than programmed.  |
| ▶ | 4:02 | Governor Mode Throttle            | Governor off, the servo moves with the throttle input channel  |
| ✖ | 4:10 | Extreme Vibration Level           | Vibrations are extreme. That means, that the measurement signal is much lower than the signal level of the vibrations. No usable flying is possible with this level. Everything has to be checked and extended tests are needed to isolate and eliminate the source of vibrations  |
| ✔ | 4:20 | Good Health Message (10sec)       | This Message describes the good health state. That means, that the VBar unit does not see any error or Info Message in the last 10 Seconds.  |
| ✔ | 4:30 | Good Health Message (10sec)       | This Message describes the good health state. That means, that the VBar unit does not see any error or Info Message in the last 10 Seconds.  |
| ✔ | 0:00 | Coldstart                         | A Coldstart is done on the beginning of each switch on time. A Coldstart can happen only, if the VBar Units is disconnected from power for more than 5 Seconds.  |
| ✔ | 0:00 | Reset Reason: Power On            | This happens if power is applied to the VBar unit. Usually this is ok, but it shall never happen in operational mode. So if a reset happens during flight, this points to a power problem. During flight the power on reset results in a warmstart. If a coldstart happens during flight, the power loss was more than 5 Seconds       |
| ▶ | 0:00 | Bank 0 Loaded                     | Bank 0 was loaded from the non volatile memory. This can be triggered by manual backswitch from the userinterface as well as in flight if bank switch is programmed to the aux channel. On Startup the Bank 0 is loaded by default.  |
| ▶ | 0:00 | Governor Mode Throttle            | Governor off, the servo moves with the throttle input channel  |
| ▶ | 0:06 | Calibration Finished              | At each Coldstart, the sensor and RC Values are calibrated to the actual seen values. If the calibration is finished, this message confirms the storage of data into the internal non volatile calibration memory  |
| ✔ | 0:16 | Good Health Message (10sec)       | This Message describes the good health state. That means, that the VBar unit does not see any error or Info Message in the last 10 Seconds.  |

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| ✔ | 0:26 | Good Health Message (10sec)       | This Message describes the good health state. That means, that the VBar unit does not see any error or Info Message in the last 10 Seconds.  |
| ✔ | 0:36 | Good Health Message (10sec)       | This Message describes the good health state. That means, that the VBar unit does not see any error or Info Message in the last 10 Seconds.  |
| ✔ | 0:46 | Good Health Message (10sec)       | This Message describes the good health state. That means, that the VBar unit does not see any error or Info Message in the last 10 Seconds.  |
| ✔ | 0:56 | Good Health Message (10sec)       | This Message describes the good health state. That means, that the VBar unit does not see any error or Info Message in the last 10 Seconds.  |
| ✔ | 1:06 | Good Health Message (10sec)       | This Message describes the good health state. That means, that the VBar unit does not see any error or Info Message in the last 10 Seconds.  |
| ✔ | 1:16 | Good Health Message (10sec)       | This Message describes the good health state. That means, that the VBar unit does not see any error or Info Message in the last 10 Seconds.  |
| ✔ | 1:26 | Good Health Message (10sec)       | This Message describes the good health state. That means, that the VBar unit does not see any error or Info Message in the last 10 Seconds.  |
| ✔ | 1:36 | Good Health Message (10sec)       | This Message describes the good health state. That means, that the VBar unit does not see any error or Info Message in the last 10 Seconds.  |
| ✔ | 1:46 | Good Health Message (10sec)       | This Message describes the good health state. That means, that the VBar unit does not see any error or Info Message in the last 10 Seconds.  |
| ▶ | 1:55 | Raised Vibration Level            | There was detected a raised level of Vibration. Since the vibration detector has to decide which signal is vibration and this is the intended measurement signal, this can happen sometimes on hard 3d moves. It shall not happen all the time. If this error is reported repeatedly very often, check the heli for vibration sources. |
| ▶ | 2:00 | Governor ON                       | Governor switched to mode ON   |
| ▶ | 2:00 | Governor is at Low Throttle Limit | There is a defined low limit, that the Governor will not fall below. If this Limit is reached, this Info Message is issued. The Message is issued once for each touch of the limit. If the limit is touched, it means that your headspeed will be higher than programmed.  |
| ▶ | 2:02 | Governor is at Low Throttle Limit | There is a defined low limit, that the Governor will not fall below. If this Limit is reached, this Info Message is issued. The Message is issued once for each touch of the limit. If the limit is touched, it means that your headspeed will be higher than programmed.  |
| ▶ | 2:04 | Governor is at Low Throttle Limit | There is a defined low limit, that the Governor will not fall below. If this Limit is reached, this Info Message is issued. The Message is issued once for each touch of the limit. If the limit is touched, it means that your headspeed will be higher than programmed.  |
| ⚠ | 2:05 | High Vibration Level              | The control loop suffers from a high vibration level, that starts to render the sensors blind. Save flying is possible, but the stability will be degraded. Additionally slow drifts that happen may be caused by vibrations.  |
| ▶ | 2:05 | Governor is at Low Throttle Limit | There is a defined low limit, that the Governor will not fall below. If this Limit is reached, this Info Message is issued. The Message is issued once for each touch of the limit. If the limit is touched, it means that your headspeed will be higher than programmed.  |
| ⚠ | 2:14 | High Vibration Level              | The control loop suffers from a high vibration level, that starts to render the sensors blind. Save flying is possible, but the stability will be degraded. Additionally slow drifts that happen may be caused by vibrations.  |
| ▶ | 2:24 | Raised Vibration Level            | There was detected a raised level of Vibration. Since the vibration detector has to decide which signal is vibration and this is the intended measurement signal, this can happen sometimes on hard 3d moves. It shall not happen all the time. If this error is reported repeatedly very often, check the heli for vibration sources. |
| ⚠ | 2:33 | High Vibration Level              | The control loop suffers from a high vibration level, that starts to render the sensors blind. Save flying is possible, but the stability will be degraded. Additionally slow drifts that happen may be caused by vibrations.  |
| ⚠ | 2:43 | High Vibration Level              | The control loop suffers from a high vibration level, that starts to render the sensors blind. Save flying is possible, but the stability will be degraded. Additionally slow drifts that happen may be caused by vibrations.  |
| ⚠ | 2:53 | High Vibration Level              | The control loop suffers from a high vibration level, that starts to render the sensors blind. Save flying is possible, but the stability will be degraded. Additionally slow drifts that happen may be caused by vibrations.  |
| ⚠ | 3:02 | High Vibration Level              | The control loop suffers from a high vibration level, that starts to render the sensors blind. Save flying is possible, but the stability will be degraded. Additionally slow drifts that happen may be caused by vibrations.  |
| ⚠ | 3:12 | High Vibration Level              | The control loop suffers from a high vibration level, that starts to render the sensors blind. Save flying is possible, but the stability will be degraded. Additionally slow drifts that happen may be caused by vibrations.  |
| ▶ | 3:21 | Raised Vibration Level            | There was detected a raised level of Vibration. Since the vibration detector has to decide which signal is vibration and this is the intended measurement signal, this can happen sometimes on hard 3d moves. It shall not happen all the time. If this error is reported repeatedly very often, check the heli for vibration sources. |
| ⚠ | 3:31 | High Vibration Level              | The control loop suffers from a high vibration level, that starts to render the sensors blind. Save flying is possible, but the stability will be degraded. Additionally slow drifts that happen may be caused by vibrations.  |
| ⚠ | 3:41 | High Vibration Level              | The control loop suffers from a high vibration level, that starts to render the sensors blind. Save flying is possible, but the stability will be degraded. Additionally slow drifts that happen may be caused by vibrations.  |
| ⚠ | 3:50 | High Vibration Level              | The control loop suffers from a high vibration level, that starts to render the sensors blind. Save flying is possible, but the stability will be degraded. Additionally slow drifts that happen may be caused by vibrations.  |

|   |      |                             |  |
|---|------|-----------------------------|--|
|    | 4:00 | High Vibration Level        | The control loop suffers from a high vibration level, that starts to render the sensors blind. Save flying is possible, but the stability will be degraded. Additionally slow drifts that happen may be caused by vibrations.  |
|    | 0:00 | Coldstart                   | A Coldstart is done on the beginning of each switch on time. A Coldstart can happen only, if the VBar Units is disconnected from power for more than 5 Seconds.  |
|    | 0:00 | Reset Reason: Power On      | This happens if power is applied to the VBar unit. Usually this is ok, but it shall never happen in operational mode. So if a reset happens during flight, this points to a power problem. During flight the power on reset results in a warmstart. If a coldstart happens during flight, the power loss was more than 5 Seconds |
|    | 0:00 | Bank 0 Loaded               | Bank 0 was loaded from the non volatile memory. This can be triggered my manual backswitch from the userinterface as well as in flight if bank switch is programmed to the aux channel. On Startup the Bank 0 is loaded by default.  |
|    | 0:00 | Governor Mode Throttle      | Governor off, the servo moves with the throttle input channel  |
|    | 0:10 | Good Health Message (10sec) | This Message describes the good health state. That means, that the VBar unit does not see any error or Info Message in the last 10 Seconds.  |
|    | 0:20 | Good Health Message (10sec) | This Message describes the good health state. That means, that the VBar unit does not see any error or Info Message in the last 10 Seconds.  |
|    | 0:30 | Good Health Message (10sec) | This Message describes the good health state. That means, that the VBar unit does not see any error or Info Message in the last 10 Seconds.  |
|    | 0:40 | Good Health Message (10sec) | This Message describes the good health state. That means, that the VBar unit does not see any error or Info Message in the last 10 Seconds.  |
|    | 0:50 | Good Health Message (10sec) | This Message describes the good health state. That means, that the VBar unit does not see any error or Info Message in the last 10 Seconds.  |
|    | 1:00 | Good Health Message (10sec) | This Message describes the good health state. That means, that the VBar unit does not see any error or Info Message in the last 10 Seconds.  |
|    | 1:10 | Good Health Message (10sec) | This Message describes the good health state. That means, that the VBar unit does not see any error or Info Message in the last 10 Seconds.  |
|    | 1:20 | Good Health Message (10sec) | This Message describes the good health state. That means, that the VBar unit does not see any error or Info Message in the last 10 Seconds.  |
|    | 1:30 | Good Health Message (10sec) | This Message describes the good health state. That means, that the VBar unit does not see any error or Info Message in the last 10 Seconds.  |
|    | 1:40 | Good Health Message (10sec) | This Message describes the good health state. That means, that the VBar unit does not see any error or Info Message in the last 10 Seconds.  |
|  | 1:50 | Good Health Message (10sec) | This Message describes the good health state. That means, that the VBar unit does not see any error or Info Message in the last 10 Seconds.  |
|  | 2:00 | Good Health Message (10sec) | This Message describes the good health state. That means, that the VBar unit does not see any error or Info Message in the last 10 Seconds.  |
|  | 2:10 | Good Health Message (10sec) | This Message describes the good health state. That means, that the VBar unit does not see any error or Info Message in the last 10 Seconds.  |
|  | 2:20 | Good Health Message (10sec) | This Message describes the good health state. That means, that the VBar unit does not see any error or Info Message in the last 10 Seconds.  |
|  | 2:30 | Good Health Message (10sec) | This Message describes the good health state. That means, that the VBar unit does not see any error or Info Message in the last 10 Seconds.  |
|  | 2:40 | Good Health Message (10sec) | This Message describes the good health state. That means, that the VBar unit does not see any error or Info Message in the last 10 Seconds.  |
|  | 2:50 | Good Health Message (10sec) | This Message describes the good health state. That means, that the VBar unit does not see any error or Info Message in the last 10 Seconds.  |
|  | 3:00 | Good Health Message (10sec) | This Message describes the good health state. That means, that the VBar unit does not see any error or Info Message in the last 10 Seconds.  |
|  | 3:10 | Good Health Message (10sec) | This Message describes the good health state. That means, that the VBar unit does not see any error or Info Message in the last 10 Seconds.  |
|  | 3:20 | Good Health Message (10sec) | This Message describes the good health state. That means, that the VBar unit does not see any error or Info Message in the last 10 Seconds.  |
|  | 3:30 | Good Health Message (10sec) | This Message describes the good health state. That means, that the VBar unit does not see any error or Info Message in the last 10 Seconds.  |
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|  | 3:50 | Good Health Message (10sec) | This Message describes the good health state. That means, that the VBar unit does not see any error or Info Message in the last 10 Seconds.  |



